



for a greener tomorrow



SSCNET III/H Sensing Module MR-MT2000 Series

August 2016

New Product Release
SV1608-4E



High Speed and High Accuracy by Synchronization of I/O Signals with Motion Control

Sensing Solutions to Add Extra Value to Your Machine

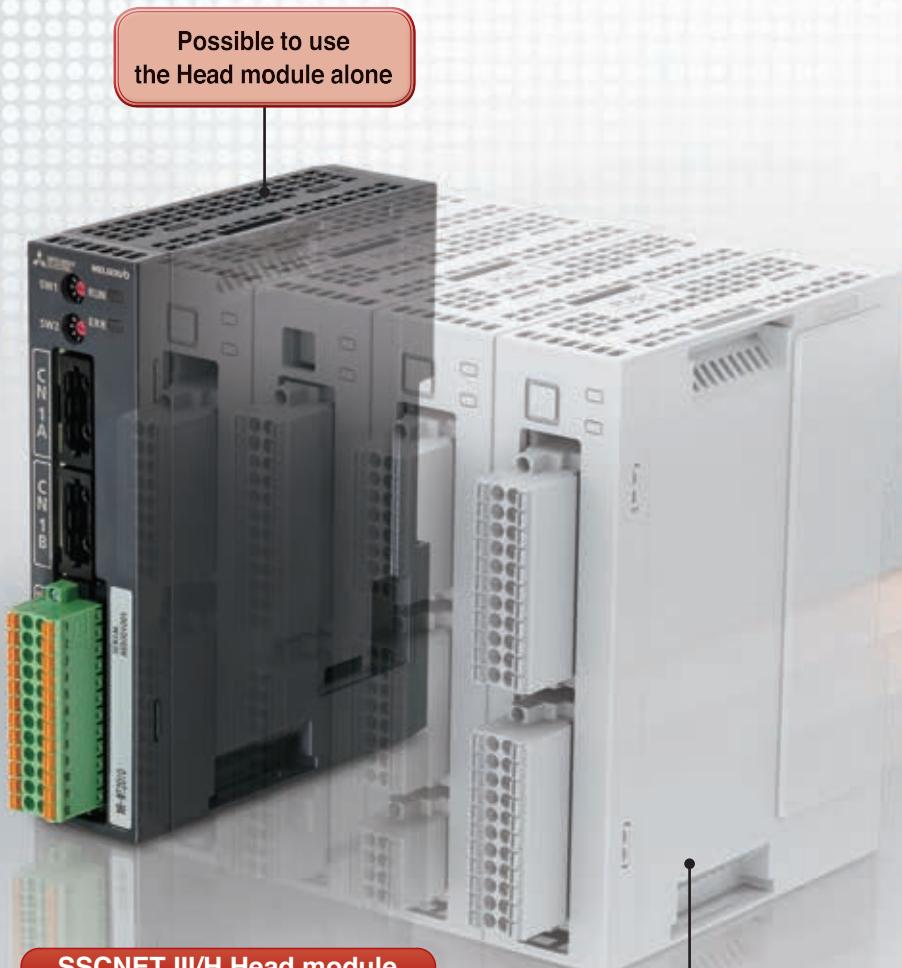
- I/O with a fastest response time of 1μs
- Pulse I/O for synchronous control
- High-accuracy analog I/O
- Supporting open standard encoder I/Fs



Sensing Module

MR-MT2000 Series

Increasing speed and accuracy of equipment by synchronization of the motion control cycle with I/Os, such as a general-purpose pulse train driver, sensor I/O, and shutter I/O



I/O module
MR-MT2100

- ▶ High-response input 16 points
- ▶ High-response output 16 points
- ▶ I/O synchronized with motion control
- ▶ A fastest response time of 1 µs
- ▶ Timing-latch input with 0.1 µs precision
- ▶ Designated-timing output with 0.1 µs precision ^(Note-1)



Production line - Machine synchronization
General-purpose pulse train drive



Pulse I/O module

MR-MT2200

- ▶ **I/O** 2CH (selectable)
- ▶ Pulse command output
- ▶ General-purpose pulse input
- ▶ Pulse-coincidence output



High-accuracy acceleration detection
High-accuracy load control



Analog I/O module

MR-MT2300

- ▶ **Input** 4CH
- ▶ **Output** 4CH
- ▶ High-resolution I/O 16 bit
- ▶ Voltage range switching function



Supporting various encoder I/Fs

Fully closed loop control



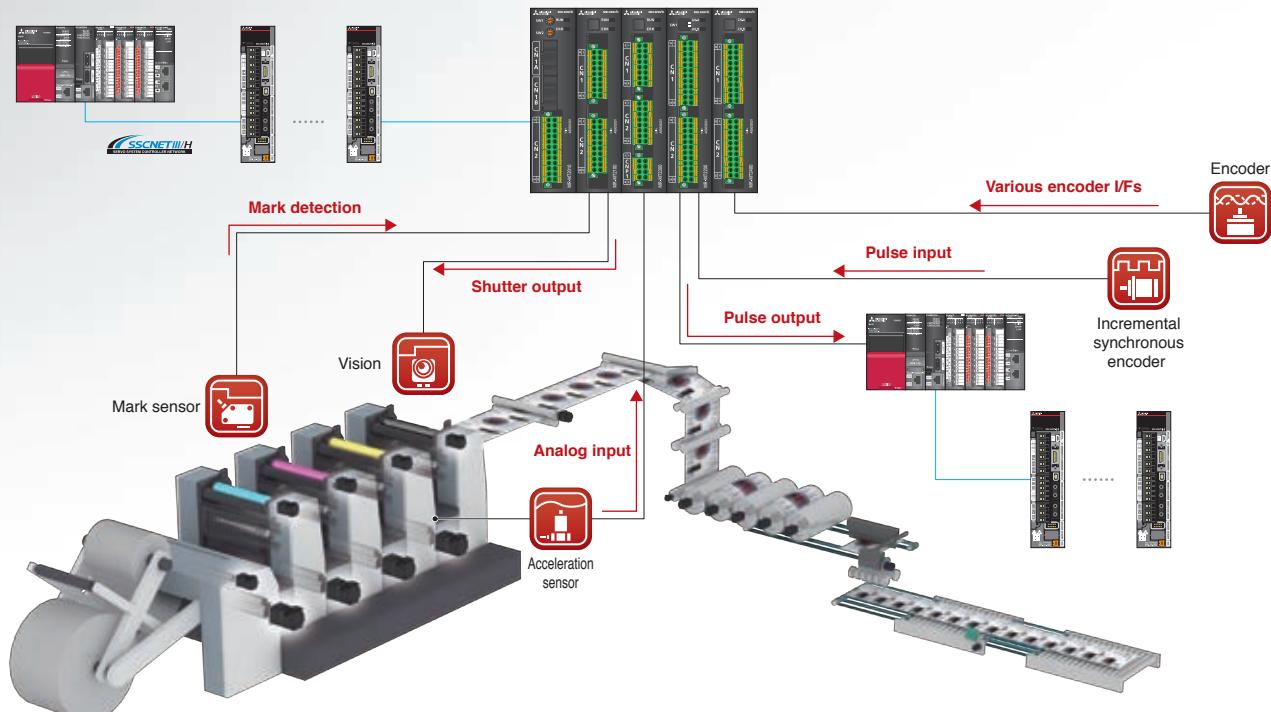
Encoder I/F module^(Note-3)

MR-MT2400

- ▶ **Input** 2CH
- ▶ SSI
- ▶ EnDat 2.2^(Note-2)
- ▶ HIPERFACE DSL®^(Note-2)
- ▶ Analog Sin/Cos^(Note-2)
- ▶ Mitsubishi Electric serial I/F^(Note-2)

(Note-2): Will be supported in the future

(Note-3): Up to two encoder I/F modules are connectable per Head module.



[Application example in printing processes]

■ Application examples to increase speed and accuracy

Issue

High-accuracy mark detection in high-speed movement

Solution

High-response mark detection with I/O module

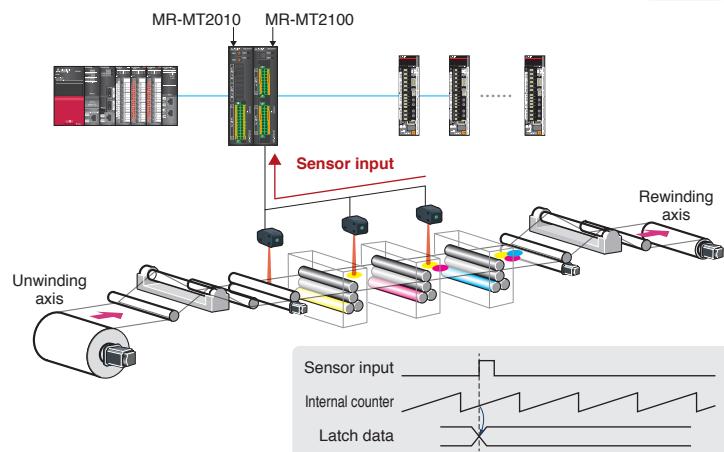


The current position is inputted every 0.1 μ s with the timing-latch input function.

Input and output can be synchronized with the motion control cycle even with the Head module alone.

[Modules to be used]

- Head module MR-MT2010
- I/O module MR-MT2100



Issue

High-accuracy imaging in high-speed movement

Solution

Shutter output with little variation by using I/O module



Output signals synchronized with the motion control cycle, can be outputted with the designated-timing output function^(Note-1), designating timing of output with 0.1 μ s precision.

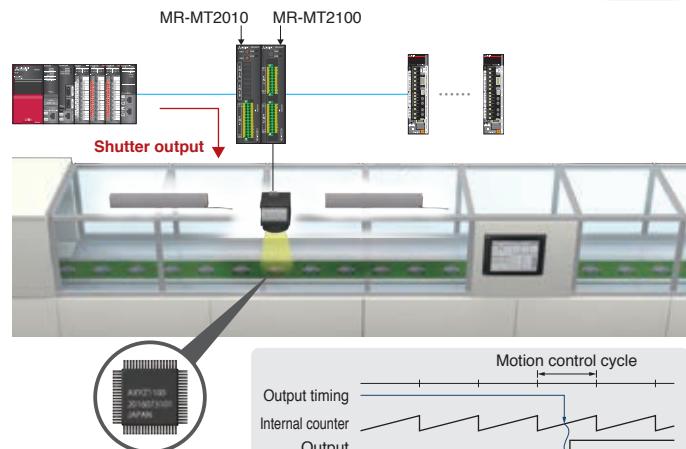
The shutter output signals with 0.1 μ s precision achieve the highly accurate imaging of the workpiece with little variation.

Input and output can be synchronized with the motion control cycle even with the Head module alone.

(Note-1): Will be available in the future

[Modules to be used]

- Head module MR-MT2010
- I/O module MR-MT2100



Issue

Load control by high-accuracy pressure detection

Solution

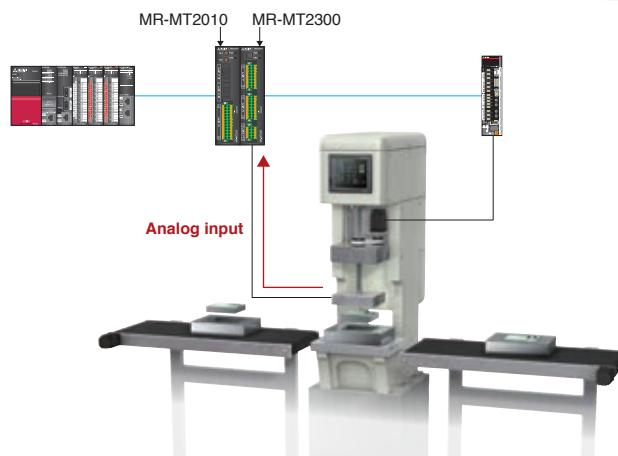
High-accuracy load control with analog I/O module



Reading pressure sensor data while synchronizing with the motion control cycle, enables I/Os with little variation and thus high-accuracy load control with a fully closed loop system.

[Modules to be used]

- Head module MR-MT2010
- Analog I/O module MR-MT2300



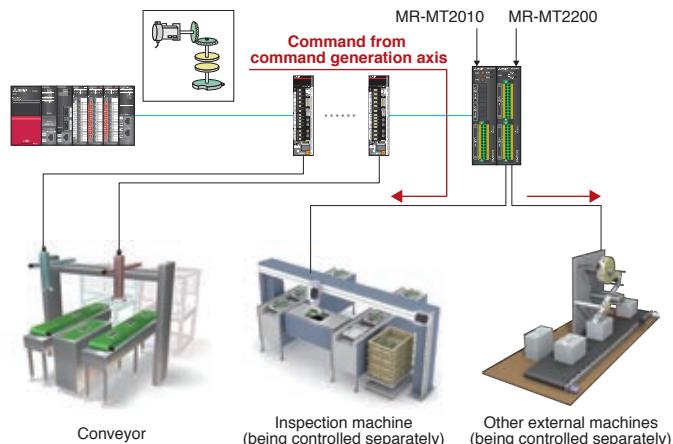
Issue**Synchronization with post processes****Solution****Synchronization of machines in the entire system with pulse I/O module**

A pulse synchronized with a command generation axis can be outputted by the current feed value of the command generation axis being transferred to a link device.

Post processes, such as an inspection machine and other external machines can be synchronized with the command generation axis even without a synchronous encoder.

[Modules to be used]

- Head module MR-MT2010
- Pulse I/O module MR-MT2200

**Issue****Use of drivers not supporting SSCNET III/H****Solution****Operating general-purpose pulse train drivers with pulse I/O module**

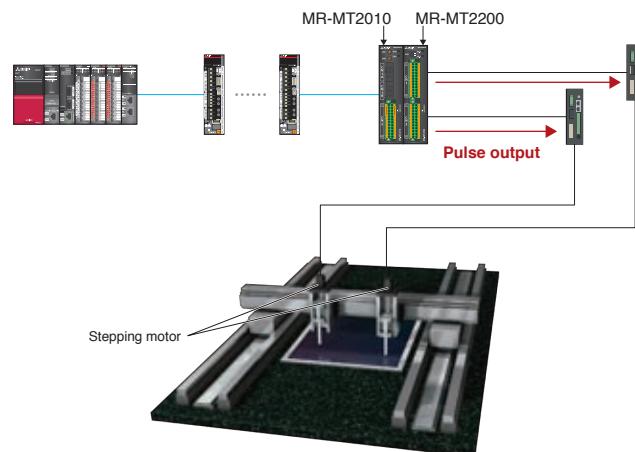
Synchronous control is possible between the general-purpose pulse train driver and the servo amplifier by SSCNET III/H connection via the SSCNET III/H Sensing modules.

(The driver is counted as a servo amplifier axis.)

(Note): MR-MT2100/2300/2400 cannot be used together with MR-MT2010/2200 when the general-purpose pulse train driver is used.

[Modules to be used]

- Head module MR-MT2010
- Pulse I/O module MR-MT2200

**Issue****Use of open standard encoders****Solution****Connecting various encoders with encoder I/F module**

The encoder I/F module supports various encoder I/Fs, enabling data input of various different encoders and thus a fully closed loop system configuration.

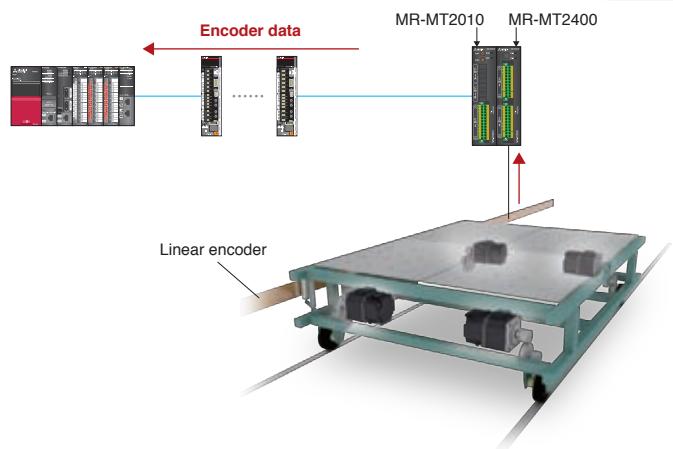
Encoder I/Fs

- SSI
- EnDat 2.2^(Note-1)
- HIPERFACE DSL[®] (Note-1)
- Analog Sin/Cos^(Note-1)
- Mitsubishi Electric serial I/F^(Note-1)

(Note-1): Will be supported in the future

[Modules to be used]

- Head module MR-MT2010
- Encoder I/F module MR-MT2400



Specifications

Name	Item		Specification		
SSCNETIII/H Head module MR-MT2010	Control circuit power supply input	Voltage	24 V DC		
		Permissible voltage fluctuation	24 V DC ± 10 %		
		Current capacity	1.0 A		
	Communications interface		SSCNET III/H		
	DI	Number of input points	12 points		
		Input method	Sink input/source input (photocoupler isolation)		
		Input response time	ON to OFF: within 1 µs/OFF to ON: within 1 µs		
	DO	Number of output points	2 points		
		Output method	Sink output (photocoupler isolation)		
		Output response time	ON to OFF: within 1 µs/OFF to ON: within 1 µs		
Mass [kg]			0.2		
I/O module MR-MT2100	DI	Number of input points	16 points ^(Note-1)		
		Input method	Sink input/source input (photocoupler isolation)		
		Input response time	ON to OFF: within 1 µs/OFF to ON: within 1 µs		
	DO	Number of output points	16 points ^(Note-1)		
		Output method	Sink output/source output ^(Note-2) (photocoupler isolation)		
		Output response time	Sink output		
			ON to OFF: within 1 µs/OFF to ON: within 1 µs		
	Source output ^(Note-2)		ON to OFF: within 2 µs/OFF to ON: within 1 µs		
	Mass [kg]		0.2		
Pulse I/O module MR-MT2200	Number of pulse I/O channels		Output 2CH, input 2CH, I/O 1CH each (selectable)		
	Pulse output	Output signal		Differential line driver output/open collector output	
		Output method		Forward/reverse rotation pulse train, signed pulse train, A-phase/B-phase pulse train	
		Maximum frequency	Differential line driver output	4M pulse/s (A-phase/B-phase pulse train 4 multiples)	
				1M pulse/s (forward/reverse rotation pulse train, signed pulse train)	
		Open collector output		200k pulse/s (A-phase/B-phase pulse train 4 multiples)	
				50k pulse/s (forward/reverse rotation pulse train, signed pulse train)	
	Pulse input	Input signal		Differential line driver input	
		Input method		Forward/reverse rotation pulse train, signed pulse train, A-phase/B-phase pulse train	
		Maximum frequency	Differential line driver input	4M pulse/s (A-phase/B-phase pulse train 4 multiples) 1M pulse/s (forward/reverse rotation pulse train, signed pulse train)	
	DI	Number of input points	7 points per axis (total of 14 points)		
		Input method	Sink input/source input (photocoupler isolation)		
		DO	5 points per axis (total of 10 points) ^(Note-3)		
	Number of output points		Sink output/source output (photocoupler isolation)		
	Mass [kg]		0.2		
Analog I/O module MR-MT2300	Analog input	Number of input channels	4CH		
		Input voltage range	-10 to 10 V DC/-5 to 5 V DC (selectable)		
		Resolution	± 10 V range: 0.334 mV ± 5 V range: 0167 mV		
		Conversion accuracy	± 0.1 % (at 25 °C)/± 0.3 % (at 0 °C to 60 °C)		
	Analog output	Number of output channels	4CH		
		Output voltage range	-10 to 10 V DC		
		Resolution	± 10 V range: 0.319 mV		
		Conversion accuracy	± 0.4 % (at 25 °C)/± 0.5 % (at 0 °C to 60 °C)		
	Mass [kg]		0.2		
	Number of encoder channels		2CH ^(Note-4)		
Encoder I/F module MR-MT2400	Supported encoder communications		SSI, EnDat 2.2 ^(Note-2) , HIPERFACE DSL ^(Note-2) , Analog Sin/Cos ^(Note-2) , Mitsubishi Electric serial I/F ^(Note-2)		
	Mass [kg]		0.2		

(Note-1): When the module is used at the temperature exceeding 55 °C and up to 60 °C, keep the number of points turned on simultaneously to be 14 for each DI and DO.

(Note-2): Will be supported in the future

(Note-3): Two of the five points and the pulse output (open collector output) are mutually exclusive.

(Note-4): Different encoder interfaces cannot be inputted for each channel. The same encoder interface should be used for both two channels.

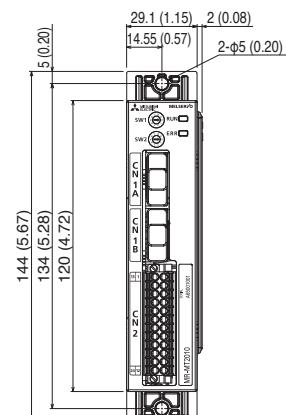
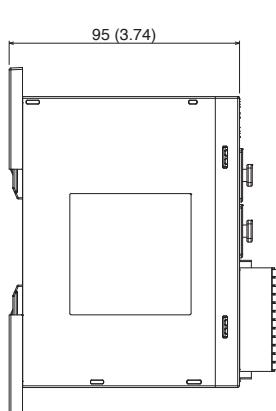
Applicable controllers

Motion CPU module	R64MTCPU, R32MTCPU, R16MTCPU
Position board ^(Note-5)	MR-MC211, MR-MC210, MR-MC241, MR-MC240
C Controller interface module ^(Note-5)	Q173SCCF

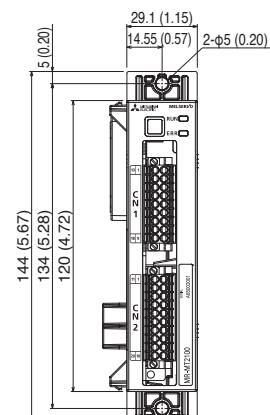
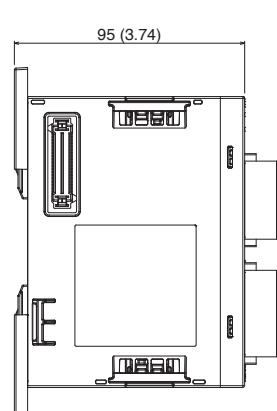
(Note-5): Will be applicable soon

■ Exterior Dimensions

SSCNET III/H Head module MR-MT2010



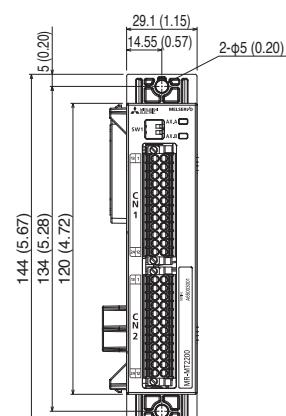
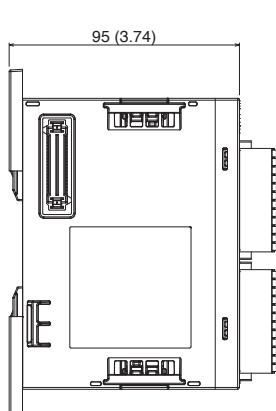
I/O module MR-MT2100



[Unit: mm (inch)]

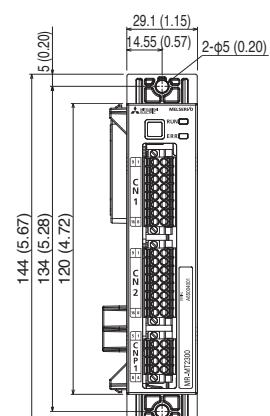
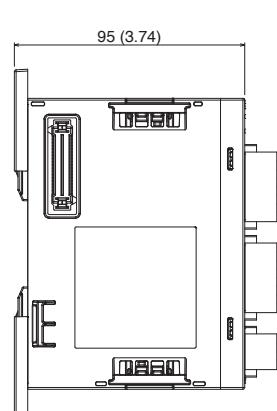
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Pulse I/O module MR-MT2200



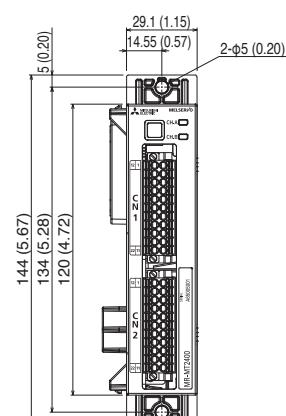
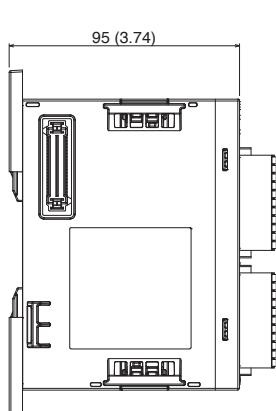
[Unit: mm (inch)]

Analog I/O module MR-MT2300



[Unit: mm (inch)]

Encoder I/F module MR-MT2400



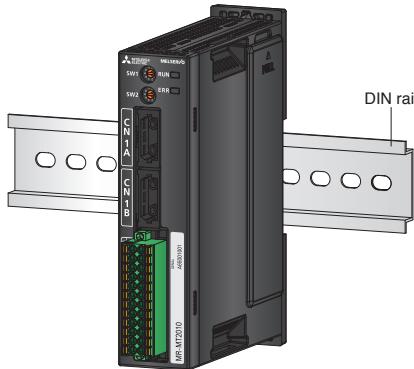
[Unit: mm (inch)]

SSCNET III/H Sensing Module MR-MT2000 Series

■ Mounting

The module is mounted either with a DIN rail or with screws.

With DIN rail



With screws



■ Product list

Name	Model	Description	Standard
SSCNET III/H Head module	MR-MT2010	SSCNET III/H communications, input: 12points, output: 2 points	UL, CE, KC, EAC
I/O module	MR-MT2100	Input 16 points, output 16 points	UL, CE, KC, EAC
Pulse I/O module	MR-MT2200	Total pulse I/O: 2CH	UL, CE, KC, EAC
Analog I/O module	MR-MT2300	Analog input: 4CH, analog output: 4CH	UL, CE, KC, EAC
Encoder I/F module	MR-MT2400	Encoder I/F: 2CH	UL, CE, KC, EAC

Safety Warning

To ensure proper use of the products listed in this catalog, please be sure to read the instruction manual prior to use.

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NAGOYA WORKS: 1-14, YADA-MINAMI 5, HIGASHI-KU, NAGOYA, JAPAN