Mitsubishi General-Purpose AC Servo

No. 14-26E

Sales and Service

Precautions for Using a Rotary Encoder on the Load-Side in the MR-J4(W)-B Fully Closed Loop System

Thank you for your continued patronage of the Mitsubishi general-purpose AC servo and FA products. For using AC servo amplifiers manufactured in May 2014 or later, the following restriction exists in the specific conditions. We ask for your understanding in this matter.

1. Target Models

MR-J4-10B to 37KB(RJ), MR-J4-10B1 to 40B1(RJ), MR-J4-60B4 to 55KB4(RJ), MR-J4W2-22B to 1010B

2. Target Period

Products manufactured between May 2014 and September 2014 (software versions BCD-B46W300 B3 and B4)

For how to check the year and month of manufacture, refer to the attachment.

3. Restriction on Specific Conditions

When all the following conditions are satisfied in the above target models:

- (1) Use of the fully closed loop system
- (2) Use of a rotary encoder (HG-KR or HG-MR) as the load-side encoder
- (3) The setting value of the fully closed loop control Feedback pulse electronic gear Numerator (FBN = [Pr.PE04] × [Pr.PE34]) satisfies the following occurrence condition.

Occurrence condition FBN = [Pr.PE04] × [Pr.PE34] ≥ 512

When all the above conditions are satisfied, AL37.1 (parameter setting range error) will occur in the servo amplifier.

However, even if the above FBN occurrence condition is satisfied, AL37.1 may not occur depending on the calculated result obtained by reducing FBN/FBD (FBN: the above equation, FBD: the setting value of the fully closed loop control - Feedback pulse electronic gear - Denominator (FBD = [Pr.PE05] × [Pr.PE35])).

In that case, customers who use the position board should check the "Phenomenon" in the following Table 1.

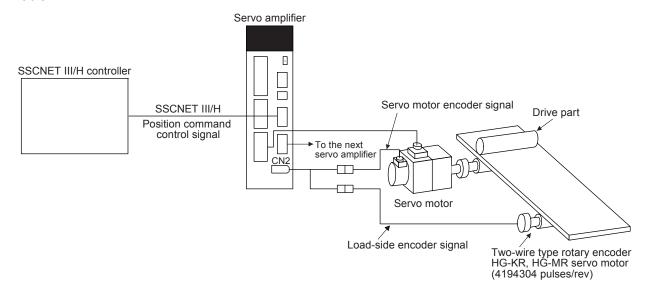


Figure 1 System configuration (for MR-J4- B servo amplifier)

Note. No problem exists when the linear scale or A/B/Z-phase differential encoder is used for load-side encoder.

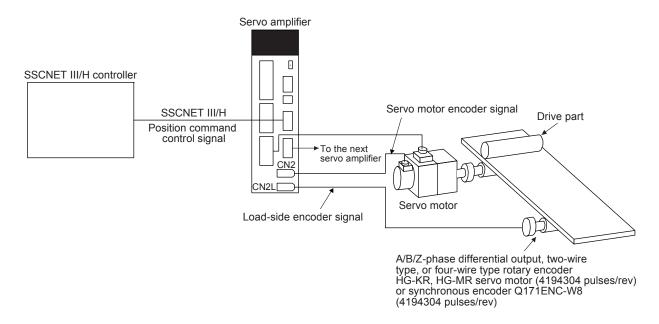


Figure 2 System configuration (for MR-J4-_B-RJ servo amplifier)

Table 1 Controller type, model and phenomenon

Controller type	Controller model	Phenomenon
Motion controller	Q172DSCPU/Q173DSCPU Q170MSCPU R16MTCPU/R32MTCPU	AL37.1 occurs.
Simple Motion module	QD77MS (2/4/16) LD77MS (2/4/16) RD77MS (2/4/8/16)	AL37.1 occurs.
Position board	MR-MC210/MR-MC211 Q173SCCF	AL37.1 occurs. (Note) When the electronic gear ratio (FBN/FBD) is less than 1, and AL37.1 does not occur, the maximum motor speed is limited by the value of the maximum motor speed × FBN/FBD.

Note. This function is not available in the J3 compatibility mode.

4. Measures to Specific Conditions

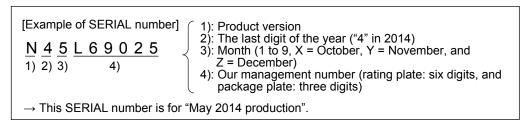
When the above specific conditions are satisfied, contact our sales representative. We will deal with the matter individually.

We ask for your understanding and arrangement in this matter.

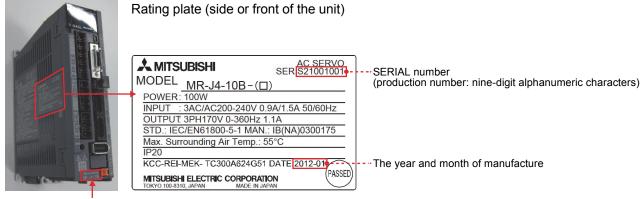
5. How to Check Target Unit

(1) How to check the year and month of manufacture

The year and month of manufacture can be checked with the SERIAL number (production number: nine-digit alphanumeric characters) printed on the side or front of the unit. You can also check the number on the packaging box.

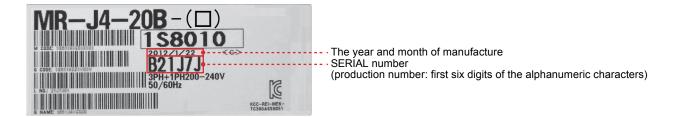


• SERIAL number (and the year and month of manufacture) on the unit



(For the capacity range having the rating plate on the side of the unit, the SERIAL number is also printed on its front.)

• SERIAL number (and the year and month of manufacture) on the packaging box



(2) How to check software version
Use MR Configurator2 to check the version as shown below.

Package plate

• Select "Diagnosis", then "System Configuration" to check the servo amplifier's S/W number.

