## Replacement of the FR-F700(P) series with FR-F800 Series (355K to 560K)

Size, connection, parameters, options concerning replacement are stated on the following pages.

## 1. REPLACING INVERTER

The FR-F800 series inverter 355K to 560 K is a separated converter type, which consists of an inverter unit (FR-F842) and a converter unit (FR-CC2).

The FR-F800 series has two specifications types: FM type and CA type.
When replacing the FR-F700(P) series of the Japanese specifications, select the FM type (FR-F842-
When the FR-F700(P) series is replaced with the FR-F800 series, the FR-F800 series does not support some FR-F700(P) series functions. For the unsupported functions, refer to section 4.2.
For achieving compliance with the shipping classification of Class NK or others, use an FR-A800 inverter.

## 2. SIZE

When the FR-F700(P) series is replaced with the FR-F800 series, the FR-F800 series 355K or higher has different installation size from that of the corresponding FR-F700(P) series.
For more information about the product size, refer to the outline dimension drawings on the following pages.

| Existing inverter | Replacing inverter | Installation size |
| :--- | :--- | :---: |
| FR-F740(P)-355K | FR-F842-355K + FR-CC2-H355K |  |
| FR-F740(P)-400K | FR-F842-400K + FR-CC2-H400K |  |
| FR-F740(P)-450K | FR-F842-450K + FR-CC2-H450K |  |
| FR-F740(P)-500K | FR-F842-500K + FR-CC2-H500K |  |
| FR-F740(P)-560K | FR-F842-560K + FR-CC2-H560K |  |

Outline dimension drawings (Unit: mm)

■FR-F740(P)-355K, 400K


■FR-F842-355K, 400K (Inverter unit)


■FR-CC2-H355K (Converter unit)


■FR-CC2-H400K (Converter unit)
3-q12 hole


■FR-F740(P)-450K, 500K, 560K


■FR-F842-450K, 500K, 560K (Inverter unit)


■FR-CC2-H450K, H500K, H560K (Converter unit)


## 3. CONNECTION

The wiring of the new inverters can follow the one of the existing inverters as the terminal names between them are almost the same.

| Type |  | F700(P) terminal name | F842 compatible terminal name | CC2 compatible terminal name |
| :---: | :---: | :---: | :---: | :---: |
| Main circuit |  | R/L1, S/L2, T/L3 | - | R/L1, S/L2, T/L3 |
|  |  | U, V, W | U, V, W | - |
|  |  | R1/L11, S1/L21 | R1/L11, S1/L21 | R1/L11, S1/L21 |
|  |  | P/+, PR | - | - |
|  |  | P/+, N/- | P/+, N/- | P/+, N/- |
|  |  | P/+, P1 | - | P1* ${ }^{\text {* }}$ |
|  |  | PR, PX | - | - |
|  |  | $\frac{1}{\square}$ | (1) | (1) |
| Control circuit input signal | Contact | STF | STF | - |
|  |  | STR | STR | - |
|  |  | STOP | STP (STOP) | - |
|  |  | RH | RH | - |
|  |  | RM | RM | - |
|  |  | RL | RL | - |
|  |  | JOG | JOG | - |
|  |  | RT | RT | - |
|  |  | $\mathrm{AU}^{*}$ | AU | - |
|  |  | CS | CS | - |
|  |  | MRS | MRS (X10) | - |
|  |  | RES | RES | RES |
|  |  | SD | SD | SD |
|  |  | PC | PC | PC |
| Analog | Frequency setting | 10E | 10E | - |
|  |  | 10 | 10 | - |
|  |  | 2 | 2 | - |
|  |  | 4 | 4 | - |
|  |  | 1 | 1 | - |
|  |  | 5 | 5 | - |
| Control circuit output signal | Relay | A1, B1, C1 | A1, B1, C1 | A1, B1, C1 |
|  |  | A2, B2, C2 | A2, B2, C2 | - |
|  | Open collector | RUN | RUN | - |
|  |  | SU | SU | - |
|  |  | OL | OL | - |
|  |  | IPF | IPF | IPF |
|  |  | FU | FU | - |
|  |  | SE | SE | SE |
|  | Pulse | FM | FM | - |
|  | Analog | AM | AM | - |
| Communication | RS-485 | PU connector | PU connector | PU connector |
| Signal for the brake unit |  | CN8 (equipped in 75K or higher) | - | - |

*1 Connection is not available.
*2 When a PTC thermistor is connected between terminals AU and SD with the AU/PTC switch set to PTC for the FR-F700(P), connect the thermistor between terminals 10 and 2 for the FR-F842.

## Main circuit terminal layout

The following shows the main circuit terminal layouts of the FR-F700(P) series and FR-F800 series.
Check the terminal names and positions before performing wiring.
When the cable used for the FR-F700(P) series is too short for the FR-F800 series, prepare the longer one.

## [400 V class]

- FR-F740(P)-355K to 560K


■FR-F842-355K to 560K (Inverter unit)


■FR-CC2-H355K to H560K (Converter unit)


*1 Do not install an MCCB across the terminals $\mathrm{P} /+$ and $\mathrm{N} /$ - (across terminals P and $\mathrm{P} /+$ or across N and $\mathrm{N} /$-). Connecting the opposite polarity of terminals $\mathrm{N} /$ - and $\mathrm{P} /+$ will damage the inverter.
*2 For the terminal used for the X 10 signal input, set "10" in any of Pr .178 to Pr .189 (input terminal function selection) to assign the function. (The X10 signal is assigned to the terminal MRS in the initial setting.)
For the X 10 signal, NC contact input specification is selected in the initial setting. Set Pr. $599=$ " 0 " to change the input specification to NO contact.
*3 For the terminal used for the X 11 signal input, set "11" in any of Pr. 178 to $\operatorname{Pr} .189$ (input terminal function selection) to assign the function. For RS-485 or any other communication where the start command is only transmitted once, use the X11 signal to save the operation mode at the time of an instantaneous power failure.
*4 Always connect the terminal RDA of the converter unit and the terminal MRS (X10) of the inverter, and the terminal SE of the converter unit and the terminal SD (sink logic) of the inverter. Not connecting these terminals may damage the converter unit.

## OOTME

- Make sure the power cables are connected to the R/L1, S/L2, and T/L3 of the converter unit. (Phase need not be matched.) Never connect the power cable to the $\mathrm{U}, \mathrm{V}$, and W of the inverter. Doing so will damage the inverter.
- Connect the motor to the $\mathrm{U}, \mathrm{V}$, and W of the inverter. (The phases must be matched.)
- When wiring the main circuit conductor, tighten a nut from the right side of the conductor.

When wiring two wires, place wires on both sides of the conductor. (Refer to the diagram below.)
For wiring, use bolts (nuts) provided with the inverter.


- When wiring the main circuit conductor (R/L1, S/L2, T/L3) of the converter unit (FR-CC2), use the bolts (nuts) for main circuit wiring, which are provided on the front side of the conductor.



## Control circuit terminal layout

The following shows the control circuit terminal layouts of the FR-F700(P) series and the FR-F800 series. The control circuit terminal layout differs between the FR-F700(P) and the FR-F800 series. Check the terminal names and positions before performing wiring.

■ Control circuit terminal layout of the FR-F700(P) series


Terminal screw size: M3.5 Tightening torque: $1.2 \mathrm{~N} \cdot \mathrm{~m}$

■ Control circuit terminal layout of the FR-F800 series

- Recommended cable gauge: 0.3 to $0.75 \mathrm{~mm}^{2}$

*1 This terminal operates as the terminal FM for the FM type, and as the terminal CA for the CA type.
*2 The $\times 10$ signal is assigned in the initial setting.
*3 No signal is assigned in the initial setting.
The control circuit terminal block intercompatibility attachment (FR-A8TAT) can be used for installing control circuit terminal blocks of the FR-F700(P) series. However, some restrictions apply for the installation. Refer to the FR-F800 catalog for the descriptions on the FR-A8TAT.


## -Wiring method

- Power supply connection

For the control circuit wiring, strip off the sheath of a cable, and use it with a blade terminal. For a single wire, strip off the sheath of the wire and apply directly.
Insert the blade terminal or the single wire into a socket of the terminal.
(1)Strip off the sheath for the below length. If the length of the sheath peeled is too long, a short circuit may occur with neighboring wires. If the length is too short, wires might come off.
Wire the stripped cable after twisting it to prevent it from becoming loose. In addition, do not solder it.

(2)Crimp the blade terminal.

Insert wires to a blade terminal, and check that the wires come out for about 0 to 0.5 mm from a sleeve.
Check the condition of the blade terminal after crimping. Do not use a blade terminal of which the crimping is inappropriate, or the face is damaged.


- Blade terminals commercially available (as of February 2012)

Phoenix Contact Co., Ltd.

| $\begin{gathered} \hline \text { Cable gauge } \\ \left(\mathrm{mm}^{2}\right) \end{gathered}$ | Blade terminal model |  |  | Crimping tool name |
| :---: | :---: | :---: | :---: | :---: |
|  | With insulation sleeve | Without insulation sleeve | For UL wire*1 |  |
| 0.3 | AI 0,5-10WH | - | - | CRIMPFOX 6 |
| 0.5 | AI 0,5-10WH | - | Al 0,5-10WH-GB |  |
| 0.75 | AI 0,75-10GY | A 0,75-10 | AI 0,75-10GY-GB |  |
| 1 | Al 1-10RD | A 1-10 | Al 1-10RD/1000GB |  |
| 1.25, 1.5 | Al 1,5-10BK | A 1,5-10 | Al 1,5-10BK/1000GB*2 |  |
| 0.75 (for two wires) | AI-TWIN $2 \times 0,75-10 \mathrm{GY}$ | - | - |  |

*1 A blade terminal with an insulation sleeve compatible with the MTW wire which has a thick wire insulation.
*2 Applicable for the terminal A1, B1, C1, A2, B2, C2.

NICHIFU Co., Ltd.

| Cable gauge <br> $\left(\mathbf{m m}^{2}\right)$ | Blade terminal product <br> number | Insulation product <br> number | Crimping tool <br> product number |
| :---: | :--- | :--- | :--- |
| 0.3 to 0.75 | $\mathrm{BT} 0.75-11$ | VC 0.75 | NH 69 |

(3)Insert the wires into a socket.


When using a single wire or stranded wires without a blade terminal, push the open/close button all the way down with a flathead screwdriver, and insert the wire.


[^0]- Wire removal

Pull the wire while pushing the open/close button all the way down firmly with a flathead screwdriver.


## NơTE:

- Pulling out the wire forcefully without pushing the open/close button all the way down may damage the terminal block.
- Use a small flathead screwdriver (tip thickness: $0.4 \mathrm{~mm} / t i p$ width: 2.5 mm )
If a flathead screwdriver with a narrow tip is used, termina block may be damaged.
Commercially available products (as of February 2012)

| Name | Model | Manufacturer |
| :---: | :--- | :---: |
| Driver | SZF |  |
|  | $0-0,4 \times 2,5$ | Phoenix Contact Co., Ltd. |

- Place the flathead screwdriver vertical to the open/close button. In case the blade tip slips, it may cause an inverter damage or injury


## 4. PARAMETER

## 4. 1. Parameter List

Although most parameter numbers are the same, some setting values differ. Refer to the following table to set the parameters. List of FR-F800 series parameters compatible with the FR-F700(P) series

The following table shows the parameter settings required when replacing an FR-F700(P) series inverter by an FR-F800 series inverter
When an FR-F700(P) series parameter is set to a value other than the initial value, set the corresponding FR-F800 parameter according to the following table.
When an FR - $\mathrm{F} 700(\mathrm{P})$ series parameter is set to an initial value, it is usually not necessary to change the corresponding FR - F 800 series parameter setting.
he parameters with $\Delta$ are used for adjustment. Set them as required.
The parameter replacement following the table below does not guarantee the inverter characteristics or performance.
Setting $\quad$ : Set the FR-F700(P) parameter as it is. The $\square$ parameters are the functions that were added to the FR-F700P series inverter.

| FR-F700(P) parameter list |  |  |  | FR-F800 compatible parameter |  |  |  | Parameter setting |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Pr. | Name | Setting range | Initial value | Pr. | Name | Setting range | Initial value | Setting | Remarks |
| 0 | Torque boost | 0 to 30\% | 1\% | 0 | Torque boost | 0 to 30\% | 1\% | $\Delta$ |  |
| 1 | Maximum frequency | 0 to 120 Hz | 60 Hz | 1 | Maximum frequency | 0 to 120 Hz | 60 Hz | $\bigcirc$ |  |
| 2 | Minimum frequency | 0 to 120 Hz | 0 Hz | 2 | Minimum frequency | 0 to 120 Hz | 0 Hz | $\bigcirc$ |  |
| 3 | Base frequency | 0 to 400 Hz | 60 Hz | 3 | Base frequency | 0 to 590 Hz | 60 Hz | $\bigcirc$ |  |
| 4 | Multi-speed setting (high speed) | 0 to 400 Hz | 60 Hz | 4 | Multi-speed setting (high speed) | 0 to 590 Hz | 60 Hz | $\bigcirc$ |  |
| 5 | Multi-speed setting (middle speed) | 0 to 400 Hz | 30 Hz | 5 | Multi-speed setting (middle speed) | 0 to 590 Hz | 30 Hz | $\bigcirc$ |  |
| 6 | Multi-speed setting (low speed) | 0 to 400 Hz | 10 Hz | 6 | Multi-speed setting (low speed) | 0 to 590 Hz | 10 Hz | $\bigcirc$ |  |
| 7 | Acceleration time | 0 to $3600 \mathrm{~s} / 0$ to 360 s | 15 s | 7 | Acceleration time | 0 to 3600 s | 15 s | $\bigcirc$ | Changing Pr. 21 after setting this parameter will change the set value. |
| 8 | Deceleration time | 0 to $3600 \mathrm{~s} / 0$ to 360 s | 30 s | 8 | Deceleration time | 0 to 3600 s | 30 s | $\bigcirc$ | Changing Pr. 21 after setting this parameter will change the set value. |
| 9 | Electronic thermal O/L relay | 0 to 3600 A | Rated output current | 9 | Electronic thermal O/L relay | 0 to 3600 A | Rated output current | $\bigcirc$ | Set the rated motor current. |
| 10 | DC injection brake operation frequency | 0 to $120 \mathrm{~Hz}, 9999$ | 3 Hz | 10 | DC injection brake operation frequency | 0 to $120 \mathrm{~Hz}, 9999$ | 3 Hz | $\bigcirc$ |  |
| 11 | DC injection brake operation time | 0 to 10 s | 0.5 s | 11 | DC injection brake operation time | 0 to $10 \mathrm{~s}, 8888$ | 0.5 s | $\bigcirc$ |  |
| 12 | DC injection brake operation voltage | 0 to 30\% | 1\% | 12 | DC injection brake operation voltage | 0 to 30\% | 1\% | $\Delta$ |  |
| 13 | Starting frequency | 0 to 60 Hz | 0.5 Hz | 13 | Starting frequency | 0 to 60 Hz | 0.5 Hz | $\bigcirc$ |  |
| 14 | Load pattern selection | 0, 1 | 1 | 14 | Load pattern selection | 0, 1 | 1 | $\bigcirc$ |  |
| 15 | Jog frequency | 0 to 400 Hz | 5 Hz | 15 | Jog frequency | 0 to 590 Hz | 5 Hz | $\bigcirc$ |  |
| 16 | Jog acceleration/deceleration time | 0 to $3600 \mathrm{~s} / 0$ to 360 s | 0.5 s | 16 | Jog acceleration/deceleration time | 0 to 3600 s | 0.5 s | $\bigcirc$ | Changing Pr. 21 after setting this parameter will change the set value. |
| 17 | MRS input selection | 0, 2, 4 | 0 | 17 | MRS input selection | 0, 2, 4 | 0 | $\bigcirc$ |  |
| 18 | High speed maximum frequency | 120 to 400 Hz | 60 Hz | 18 | High speed maximum frequency | 0 to 590 Hz | 60 Hz | $\bigcirc$ |  |
| 19 | Base frequency voltage | 0 to $1000 \mathrm{~V}, 8888,9999$ | 9999 | 19 | Base frequency voltage | 0 to $1000 \mathrm{~V}, 8888,9999$ | 9999 | $\bigcirc$ |  |
| 20 | Acceleration/deceleration reference frequency | 1 to 400 Hz | 60 Hz | 20 | Acceleration/deceleration reference frequency | 1 to 590 Hz | 60 Hz | $\bigcirc$ |  |
| 21 | Acceleration/deceleration time increments | 0, 1 | 0 | 21 | Acceleration/deceleration time increments | 0, 1 | 0 | $\bigcirc$ |  |
| 22 | Stall prevention operation level | 0 to 150\%, 9999 | 120\% | 22 | Stall prevention operation level | 0 to 400\% | 120\% | $\Delta$ | When the FR-F700(P) setting is "9999", set Pr. 868 = " 4 " and use the initial setting of Pr. 22 for the FR-F800. |
| 23 | Stall prevention operation level compensation factor at double speed | 0 to 200\%, 9999 | 9999 | 23 | Stall prevention operation level compensation factor at double speed | 0 to 200\%, 9999 | 9999 | $\bigcirc$ |  |



| FR-F700(P) parameter list |  |  |  | FR-F800 compatible parameter |  |  |  | Parameter setting |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Pr. | Name | Setting range | Initial value | Pr. | Name | Setting range | Initial value | Setting | Remarks |
| 67 | Number of retries at fault occurrence | 0 to 10, 101 to 110 | 0 | 67 | Number of retries at fault occurrence | 0 to 10, 101 to 110 | 0 | $\bigcirc$ |  |
| 68 | Retry waiting time | 0 to 10 s | 1 s | 68 | Retry waiting time | 0.1 to 600 s | 1 s | $\Delta$ | $\begin{aligned} & \hline \text { FR-F700(P) } \rightarrow \text { FR-F800 } \\ & 0 \rightarrow 0.1 \mathrm{~s} \end{aligned}$ |
| 69 | Retry count display erase | 0 | 0 | 69 | Retry count display erase | 0 | 0 | $\times$ |  |
| 70 | Special regenerative brake duty | 0 to 10\% | 0\% | 70 | - | - | - | - | Parameter for manufacturer setting. Do not set. |
| 71 | Applied motor | 0, 1, 2, 20, 120, 210, 2010, 2110 | 0 | 71 | Applied motor | 0 to 6,13 to $16,20,23,24,40,43,44$, 50, 53, 54, 70, 73, 74, 210, 213, 214, 8090, 8093, 8094, 9090, 9093, 9094 | 0 | $\Delta$ | Set as follows: <br> "120" for the F700(P) $\rightarrow$ "8090" for the F800 |
| 72 | PWM frequency selection | 0 to 6, 25 | 2 | 72 | PWM frequency selection | 0 to 6, 25 | 2 | $\bigcirc$ |  |
| 73 | Analog input selection | 0 to 7, 10 to 17 | 1 | 73 | Analog input selection | 0 to 7, 10 to 17 | 1 | $\bigcirc$ |  |
| 74 | Input filter time constant | 0 to 8 | 1 | 74 | Input filter time constant | 0 to 8 | 1 | $\bigcirc$ |  |
| 75 | Reset selection/disconnected PU detection/PU stop selection | 0 to 3, 14 to 17 | 14 | 75 | Reset selection/disconnected PU detection/PU stop selection | 0 to 3, 14 to 17, 100 to 103, 114 to 117 | 14 | $\bigcirc$ |  |
| 76 | Fault code output selection | 0, 1, 2 | 0 | 76 | Fault code output selection | 0, 1, 2 | 0 | $\bigcirc$ |  |
| 77 | Parameter write selection | 0, 1, 2 | 0 | 77 | Parameter write selection | 0, 1, 2 | 0 | $\bigcirc$ |  |
| 78 | Reverse rotation prevention selection | 0,1,2 | 0 | 78 | Reverse rotation prevention selection | 0, 1, 2 | 0 | $\bigcirc$ |  |
| 79 | Operation mode selection | 0 to 4, 6 to 7 | 0 | 79 | Operation mode selection | 0 to 4, 6 to 7 | 0 | $\bigcirc$ |  |
| 80 | Motor capacity | 0 to $3600 \mathrm{~kW}, 9999$ | 9999 | 80 | Motor capacity | 0 to $3600 \mathrm{~kW}, 9999$ | 9999 | $\bigcirc$ | Set this parameter according to the motor. <br> When Pr. $80=$ "9999" and Pr. $71 \neq " 120,210,2010$, or 2110 " for the FR-F700(P), set Pr. $81=$ "4" and Pr. 89 = "0" for the FR-F800. |
|  |  |  |  | 81 | Number of motor poles | 2, 4, 6, 8, 10, 12, 9999 | 9999 | $\times$ |  |
|  |  |  |  | 89 | Speed control gain | 0 to 200\%, 9999 | 9999 | $\times$ |  |
| 90 | Motor constant (R1) | 0 to $400 \mathrm{~m} \Omega$, 9999 | 9999 | 90 | Motor constant (R1) | 0 to $400 \mathrm{~m} \Omega$, 9999 | 9999 | $\bigcirc$ |  |
|  |  |  |  |  | Online auto tuning selection | 0 to 2 | 0 | $\bigcirc$ |  |
|  |  |  |  |  | Auto tuning setting/status | 0, 1, 11, 101 | 0 | $\Delta$ | If auto tuning has been performed, perform tuning again as required. |
| 100 | V/F1 (first frequency) | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 100 | V/F1 (first frequency) | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 101 | V/F1 (first frequency voltage) | 0 to 1000 V | 0 V | 101 | V/F1 (first frequency voltage) | 0 to 1000 V | 0 V | $\bigcirc$ |  |
| 102 | V/F2 (second frequency) | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 102 | V/F2 (second frequency) | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 103 | V/F2 (second frequency voltage) | 0 to 1000 V | 0 V | 103 | V/F2 (second frequency voltage) | 0 to 1000 V | 0 V | $\bigcirc$ |  |
| 104 | V/F3 (third frequency) | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 104 | V/F3 (third frequency) | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 105 | V/F3 (third frequency voltage) | 0 to 1000 V | 0 V | 105 | V/F3 (third frequency voltage) | 0 to 1000 V | 0 V | $\bigcirc$ |  |
| 106 | V/F4 (fourth frequency) | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 106 | V/F4 (fourth frequency) | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 107 | V/F4 (fourth frequency voltage) | 0 to 1000 V | 0 V | 107 | V/F4 (fourth frequency voltage) | 0 to 1000 V | 0 V | $\bigcirc$ |  |
| 108 | V/F5 (fifth frequency) | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 108 | V/F5 (fifth frequency) | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 109 | V/F5 (fifth frequency voltage) | 0 to 1000 V | 0V | 109 | V/F5 (fifth frequency voltage) | 0 to 1000 V | 0 V | $\bigcirc$ |  |


| FR-F700(P) parameter list |  |  |  | FR-F800 compatible parameter |  |  |  | Parameter setting |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Pr. | Name | Setting range | Initial value | Pr. | Name | Setting range | Initial value | Setting | Remarks |
| 117 | PU communication station number | 0 to 31 | 0 | 117 | PU communication station number | 0 to 31 | 0 | $\bigcirc$ |  |
| 118 | PU communication speed | 48, 96, 192, 384 | 192 | 118 | PU communication speed | $\begin{gathered} 48,96,192,384,576,768, \\ 1152 \end{gathered}$ | 192 | $\bigcirc$ |  |
| 119 | PU communication stop bit length | 0, 1, 10, 11 | 1 | 119 | PU communication stop bit length / data length | 0, 1, 10, 11 | 1 | $\bigcirc$ |  |
| 120 | PU communication parity check | 0, 1, 2 | 2 | 120 | PU communication parity check | 0, 1, 2 | 2 | $\bigcirc$ |  |
| 121 | Number of PU communication retries | 0 to 10, 9999 | 1 | 121 | PU communication retry count | 0 to 10, 9999 | 1 | $\bigcirc$ |  |
| 122 | PU communication check time interval | 0, 0.1 to $999.8 \mathrm{~s}, 9999$ | 9999 | 122 | PU communication check time interval | 0, 0.1 to $999.8 \mathrm{~s}, 9999$ | 9999 | $\bigcirc$ |  |
| 123 | PU communication waiting time setting | 0 to $150 \mathrm{~ms}, 9999$ | 9999 | 123 | PU communication waiting time setting | 0 to $150 \mathrm{~ms}, 9999$ | 9999 | $\bigcirc$ |  |
| 124 | PU communication CR/LF selection | 0, 1, 2 | 1 | 124 | PU communication CR/LF selection | 0, 1, 2 | 1 | $\bigcirc$ |  |
| 125 | Terminal 2 frequency setting gain frequency | 0 to 400 Hz | 60 Hz | 125 | Terminal 2 frequency setting gain frequency | 0 to 590 Hz | 60 Hz | $\bigcirc$ |  |
| 126 | Terminal 4 frequency setting gain frequency | 0 to 400 Hz | 60 Hz | 126 | Terminal 4 frequency setting gain frequency | 0 to 590 Hz | 60 Hz | $\bigcirc$ |  |
| 127 | PID control automatic switchover frequency | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 127 | PID control automatic switchover frequency | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 128 | PID action selection | $\begin{gathered} 10,11,20,21,50,51,60,61 \\ 110,111,120,121 \end{gathered}$ | 10 | 128 | PID action selection | $0,10,11,20,21,50,51,60$, $61,70,71,80,81,90,91,100$, 101, 1000, 1001, 1010, 1011, 2000, 2001, 2010, 2011 | 0 | $\Delta$ | When "14" (X14 signal) is not set in any parameter from Pr. 178 to Pr. 189, or when PID control is not used even if "14" (X14 signal) is set in a parameter from Pr. 178 to Pr. 189 in the FR-F700(P), set "0" in Pr. 128 in the FR-F800. When the X 14 signal is not assigned to any input terminal, just set Pr. 128 to enable PID control in the FR-F800. |
| 129 | PID proportional band | 0.1 to 1000\%, 9999 | 100\% | 129 | PID proportional band | 0.1 to 1000\%, 9999 | 100\% | $\bigcirc$ |  |
| 130 | PID integral time | 0.1 to $3600 \mathrm{~s}, 9999$ | 1 s | 130 | PID integral time | 0.1 to $3600 \mathrm{~s}, 9999$ | 1 s | $\bigcirc$ |  |
| 131 | PID upper limit | 0 to 100\%, 9999 | 9999 | 131 | PID upper limit | 0 to 100\%, 9999 | 9999 | $\bigcirc$ |  |
| 132 | PID lower limit | 0 to 100\%, 9999 | 9999 | 132 | PID lower limit | 0 to 100\%, 9999 | 9999 | $\bigcirc$ |  |
| 133 | PID action set point | 0 to 100\%, 9999 | 9999 | 133 | PID action set point | 0 to 100\%, 9999 | 9999 | $\bigcirc$ |  |
| 134 | PID differential time | 0.01 to $10.00 \mathrm{~s}, 9999$ | 9999 | 134 | PID differential time | 0.01 to $10.00 \mathrm{~s}, 9999$ | 9999 | $\bigcirc$ |  |
| 135 | Electronic bypass sequence selection | 0, 1 | 0 | 135 | Electronic bypass sequence selection | 0, 1 | 0 | $\bigcirc$ |  |
| 136 | MC switchover interlock time | 0 to 100 s | 1 s | 136 | MC switchover interlock time | 0 to 100 s | 1 s | $\bigcirc$ |  |
| 137 | Start waiting time | 0 to 100 s | 0.5 s | 137 | Start waiting time | 0 to 100 s | 0.5 s | $\bigcirc$ |  |
| 138 | Bypass selection at a fault | 0, 1 | 0 | 138 | Bypass selection at a fault | 0, 1 | 0 | $\bigcirc$ |  |
| 139 | Automatic switchover frequency from inverter to bypass operation | 0 to $60 \mathrm{~Hz}, 9999$ | 9999 | 139 | Automatic switchover frequency from inverter to bypass operation | 0 to $60 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 140 | Backlash acceleration stopping frequency | 0 to 400 Hz | 1 Hz | 140 | Backlash acceleration stopping frequency | 0 to 590 Hz | 1 Hz | $\bigcirc$ |  |
| 141 | Backlash acceleration stopping time | 0 to 360 s | 0.5 s | 141 | Backlash acceleration stopping time | 0 to 360 s | 0.5 s | $\bigcirc$ |  |
| 142 | Backlash deceleration stopping frequency | 0 to 400 Hz | 1 Hz | 142 | Backlash deceleration stopping frequency | 0 to 590 Hz | 1 Hz | $\bigcirc$ |  |
| 143 | Backlash deceleration stopping time | 0 to 360 s | 0.5 s | 143 | Backlash deceleration stopping time | 0 to 360 s | 0.5 s | $\bigcirc$ |  |
| 144 | Speed setting switchover | $\begin{gathered} 0,2,4,6,8,10,102,104 \\ 106,108,110 \\ \hline \end{gathered}$ | 4 | 144 | Speed setting switchover | $\begin{gathered} 0,2,4,6,8,10,12,102,104, \\ 106,108,110,112 \\ \hline \end{gathered}$ | 4 | $\bigcirc$ |  |
| 145 | PU display language selection | 0 to 7 | 0 | 145 | PU display language selection | 0 to 7 | 1 | $\bigcirc$ |  |
| 147 | Acceleration/deceleration time switchover frequency | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 147 | Acceleration/deceleration time switchover frequency | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 148 | Stall prevention level at 0 V input | 0 to 150\% | 120\% | 148 | Stall prevention level at 0 V input | 0 to 400\% | 120\% | $\bigcirc$ |  |
| 149 | Stall prevention level at 10 V input | 0 to 150\% | 120\% | 149 | Stall prevention level at 10 V input | 0 to 400\% | 150\% | $\bigcirc$ |  |
| 150 | Output current detection level | 0 to 150\% | 120\% | 150 | Output current detection level | 0 to 400\% | 120\% | $\bigcirc$ |  |
| 151 | Output current detection signal delay time | 0 to 10 s | 0 s | 151 | Output current detection signal delay time | 0 to 10 s | 0 s | $\bigcirc$ |  |
| 152 | Zero current detection level | 0 to 150\% | 5\% | 152 | Zero current detection level | 0 to 400\% | 5\% | $\bigcirc$ |  |
| 153 | Zero current detection time | 0 to 10 s | 0.5 s | 153 | Zero current detection time | 0 to 10 s | 0.5 s | $\bigcirc$ |  |
| 154 | Voltage reduction selection during stall prevention operation | 0, 1, 10, 11 | 1 | 154 | Voltage reduction selection during stall prevention operation | 0, 1, 10, 11 | 1 | $\bigcirc$ |  |
| 155 | RT signal function validity condition selection | 0, 10 | 0 | 155 | RT signal function validity condition selection | 0, 10 | 0 | $\bigcirc$ |  |


| FR－F700（P）parameter list |  |  |  | FR－F800 compatible parameter |  |  |  | Parameter setting |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Pr． | Name | Setting range | Initial value | Pr． | Name | Setting range | Initial value | Setting | Remarks |
| 156 | Stall prevention operation selection | 0 to 31，100， 101 | 0 | 156 | Stall prevention operation selection | 0 to 31，100， 101 | 0 | $\bigcirc$ |  |
| 157 | OL signal output timer | 0 to $25 \mathrm{~s}, 9999$ | 0 s | 157 | OL signal output timer | 0 to $25 \mathrm{~s}, 9999$ | 0 s | $\bigcirc$ |  |
| 158 | AM terminal function selection | $\begin{gathered} 1 \text { to } 3,5,6,8 \text { to } 14,17,21,24, \\ 50,52,53 \\ \hline \end{gathered}$ | 1 | 158 | AM terminal function selection | 1 to 3,5 to 14，17，18，21， 2434,50 ， 52 to $54,61,62,67,70,86$ to 96,98 | 1 | $\bigcirc$ |  |
| 159 | Automatic switchover frequency range from bypass to inverter operation | 0 to $10 \mathrm{~Hz}, 9999$ | 9999 | 159 | Automatic switchover frequency range from bypass to inverter operation | 0 to $10 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 160 | User group read selection | 0，1， 9999 | 9999 | 160 | User group read selection | 0，1， 9999 | 9999 | $\bigcirc$ |  |
| 161 | Frequency setting／key lock operation selection | 0，1，10， 11 | 0 | 161 | Frequency setting／key lock operation selection | 0，1，10， 11 | 0 | $\bigcirc$ |  |
| 162 | Automatic restart after instantaneous power failure selection | 0，1，10， 11 | 0 | 162 | Automatic restart after instantaneous power failure selection | 0 to 3， 10 to 13 | 0 | $\bigcirc$ |  |
| 163 | First cushion time for restart | 0 to 20 s | 0 s | 163 | First cushion time for restart | 0 to 20 s | 0 s | $\bigcirc$ |  |
| 164 | First cushion voltage for restart | 0 to 100\％ | 0\％ | 164 | First cushion voltage for restart | 0 to 100\％ | 0\％ | $\bigcirc$ |  |
| 165 | Stall prevention operation level for restart | 0 to 150\％ | 120\％ | 165 | Stall prevention operation level for restart | 0 to 400\％ | 120\％ | $\bigcirc$ |  |
| 166 | Output current detection signal retention time | 0 to $10 \mathrm{~s}, 9999$ | 0.1 s | 166 | Output current detection signal retention time | 0 to $10 \mathrm{~s}, 9999$ | 0.1 s | $\bigcirc$ |  |
| 167 | Output current detection operation selection | 0，1，10， 11 | 0 | 167 | Output current detection operation selection | 0，1，10， 11 | 0 | $\bigcirc$ |  |
| 170 | Watt－hour meter clear | 0，10， 9999 | 9999 | 170 | Watt－hour meter clear | 0，10， 9999 | 9999 | $\times$ | Setting not required |
| 171 | Operation hour meter clear | 0，9999 | 9999 | 171 | Operation hour meter clear | 0，9999 | 9999 | $\times$ | Setting not required |
| 172 | User group registered display／batch clear | 9999，（0 to 16） | 0 | 172 | User group registered display／batch clear | 9999，（0 to 16） | 0 | $\times$ |  |
| 173 | User group registration | 0 to 999， 9999 | 9999 | 173 | User group registration | 0 to 1999， 9999 | 9999 | $\times$ | Set the parameter as required． |
| 174 | User group clear | 0 to 999， 9999 | 9999 | 174 | User group clear | 0 to 1999， 9999 | 9999 | $\times$ |  |
| 178 | STF terminal function selection | 0 to 8,10 to $12,14,16,24,25,60$ ， 62,64 to 67,70 to 72,9999 | 60 | 178 | STF terminal function selection | $\begin{gathered} \hline 0 \text { to } 8,10 \text { to } 14,16,18,24,25,28,37 \\ \text { to } 40,46 \text { to } 48,50,51,60,62,64 \text { to } \\ 67,70 \text { to } 73,77 \text { to } 81,84,94 \text { to } 98, \\ 9999 \\ \hline \end{gathered}$ | 60 | $\bigcirc$ | The setting values＂ 70 and 71 ＂cannot be selected． <br> The three terminals， $\mathrm{X} 10, \mathrm{X} 11$ ，and RES are required for the connection with the |
| 179 | STR terminal function selection | 0 to 8,10 to $12,14,16,24,25,61$ ， 62， 64 to 67,70 to 72,9999 | 61 | 179 | STR terminal function selection | ```O to 8, 10 to 14, 16, 18, 24, 25, 28, 37 to 40,46 to 48,50,51,60,62,64 to 67,70 to 73,77 to 81, 84,94 to 98, 9999``` | 61 | $\bigcirc$ | FR－CC2． <br> In the initial setting，the X 10 signal is assigned to terminal MRS，and the RES signal to terminal RES．When these |
| 180 | RL terminal function selection | 0 to 8,10 to $12,14,16,24,25$ ， 62,64 to 67,70 to 72,9999 | 0 | 180 | RL terminal function selection | 0 to 8,10 to 14，16，18，24，25，28， 37 to 40,46 to $48,50,51,62,64$ to 67 ， 70 to 73,77 to $81,84,94$ to 98,9999 | 0 | $\bigcirc$ | terminals of the FR－F700（P）are used，use |
| 181 | RM terminal function selection |  | ， | 181 | RM terminal function selection |  | 1 | $\bigcirc$ | other terminals of the FR－F800 |
| 182 | RH terminal function selection |  | 2 | 182 | RH terminal function selection |  | 2 | $\bigcirc$ |  |
| 183 | RT terminal function selection |  | 3 | 183 | RT terminal function selection |  | 3 | $\bigcirc$ |  |
| 184 | AU terminal function selection | $\begin{gathered} 0 \text { to } 8,10 \text { to } 12,14,16,24,25, \\ 62 \text { to } 67,70 \text { to } 72,9999 \end{gathered}$ | 4 | 184 | AU terminal function selection |  | 4 | $\bigcirc$ |  |
| 185 | JOG terminal function selection | 0 to 8,10 to $12,14,16,24,25,62$ ， <br> 64 to 67,70 to 72,9999 | 5 | 185 | JOG terminal function selection |  | 5 | $\bigcirc$ |  |
| 186 | CS terminal function selection |  | 6 | 186 | CS terminal function selection |  | 9999 | $\Delta$ |  |
| 187 | MRS terminal function selection |  | 24 | 187 | MRS terminal function selection |  | 10 | $\Delta$ |  |
| 188 | STOP terminal function selection |  | 25 | 188 | STOP terminal function selection |  | 25 | $\bigcirc$ |  |
| 189 | RES terminal function selection |  | 62 | 189 | RES terminal function selection |  | 62 | $\bigcirc$ |  |


| FR－F700（P）parameter list |  |  |  | FR－F800 compatible parameter |  |  |  | Parameter setting |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Pr． | Name | Setting range | Initial value | Pr． | Name | Setting range | Initial value | Setting | Remarks |
| 190 | RUN terminal function selection | 0 to 5，7，8， 10 to 19，25，26， 45 to $48,57,64,67,70,79,85,90$ ， 91， $92,93,94$ to $96,98,99,100$ to $105,107,108,110$ to 116 ， $125,126,145$ to $148,157,164$ ， 167，170，179，185，190，191， 192，193， 194 to 196，198，199， 9999 | 0 | 190 | RUN terminal function selection | 0 to $5,7,8,10$ to $19,25,26,35,39,40$ ， 45 to $54,57,64$ to 68,70 to $79,82,85$ ， 90 to 96,98 to $105,107,108,110$ to 116，125，126，135，139，140， 145 to $154,157,164$ to 168,170 to 179,182 ， 185， 190 to 196,198 to 208， 211 to $213,215,300$ to 308,311 to 313 ， 315， 9999 | 0 | $\bigcirc$ | For driving IPM，set the FB and FB2 signals instead of the FU and FU2 signals． |
| 191 | SU terminal function selection |  | 1 | 191 | SU terminal function selection |  | 1 | $\bigcirc$ |  |
| 192 | IPF terminal function selection |  | 2 | 192 | IPF terminal function selection |  | 9999 | $\Delta$ |  |
| 193 | OL terminal function selection |  | 3 | 193 | OL terminal function selection |  | 3 | $\bigcirc$ |  |
| 194 | FU terminal function selection |  | 4 | 194 | FU terminal function selection |  | 4 | $\bigcirc$ |  |
| 195 | ABC1 terminal function selection | 0 to $5,7,8,10$ to 19，25，26， 45 to $48,57,64,67,70,79,85,90$ ， 91，92，93， 94 to $96,98,99,100$ to $105,107,108,110$ to 116 ， $125,126,145$ to $148,157,164$ ， 167，170，179，185，190，191， 192，193， 194 to 196，198，199， 9999 | 99 | 195 | ABC1 terminal function selection | 0 to $5,7,8,10$ to 19，25，26，35，39，40， 45 to $54,57,64$ to 68,70 to $79,82,85$ ， 90，91， 94 to 96,98 to 105，107，108， 110 to $116,125,126,135,139,140$ ， 145 to $154,157,164$ to 168,170 to 179，182，185，190，191， 194 to 196， 198 to 208,211 to $213,215,300$ to 308 ， 311 to $313,315,9999$ | 99 | $\bigcirc$ |  |
| 196 | ABC2 terminal function selection |  | 9999 | 196 | ABC2 terminal function selection |  | 9999 | $\bigcirc$ |  |
| 232 | Multi－speed setting（speed 8） | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 232 | Multi－speed setting（speed 8） | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 233 | Multi－speed setting（speed 9） | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 233 | Multi－speed setting（speed 9） | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 234 | Multi－speed setting（speed 10） | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 234 | Multi－speed setting（speed 10） | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 235 | Multi－speed setting（speed 11） | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 235 | Multi－speed setting（speed 11） | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 236 | Multi－speed setting（speed 12） | 0 to 400 Hz ， 9999 | 9999 | 236 | Multi－speed setting（speed 12） | 0 to 590 Hz ， 9999 | 9999 | $\bigcirc$ |  |
| 237 | Multi－speed setting（speed 13） | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 237 | Multi－speed setting（speed 13） | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 238 | Multi－speed setting（speed 14） | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 238 | Multi－speed setting（speed 14） | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 239 | Multi－speed setting（speed 15） | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 239 | Multi－speed setting（speed 15） | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 240 | Soft－PWM operation selection | 0， 1 | 1 | 240 | Soft－PWM operation selection | 0， 1 |  | $\bigcirc$ |  |
| 241 | Analog input display unit switchover | 0，1 | 0 | 241 | Analog input display unit switchover | 0， 1 | 0 | $\bigcirc$ |  |
| 242 | Terminal 1 added compensation amount（terminal 2） | 0 to 100\％ | 100\％ | 242 | Terminal 1 added compensation amount（terminal 2） | 0 to 100\％ | 100\％ | $\bigcirc$ |  |
| 243 | Terminal 1 added compensation amount（terminal 4） | 0 to 100\％ | 75\％ | 243 | Terminal 1 added compensation amount（terminal 4） | 0 to 100\％ | 75\％ | $\bigcirc$ |  |
| 244 | Cooling fan operation selection | 0， 1 | 1 | 244 | Cooling fan operation selection | 0，1， 101 to 105 | 1 | $\bigcirc$ |  |
| 245 | Rated slip | 0 to 50\％， 9999 | 9999 | 245 | Rated slip | 0 to 50\％， 9999 | 9999 | $\bigcirc$ |  |
| 246 | Slip compensation time constant | 0.01 to 10 s | 0.5 s | 246 | Slip compensation time constant | 0.01 to 10 s | 0.5 s | $\bigcirc$ |  |
| 247 | Constant－output range slip compensation selection | 0，9999 | 9999 | 247 | Constant－output range slip compensation selection | 0，9999 | 9999 | $\bigcirc$ |  |
| 250 | Stop selection | $\begin{gathered} 0 \text { to } 100 \mathrm{~s}, 1000 \text { to } 1100 \mathrm{~s}, 8888 \text {, } \\ 9999 \end{gathered}$ | 9999 | 250 | Stop selection | 0 to $100 \mathrm{~s}, 1000$ to $1100 \mathrm{~s}, 8888,9999$ | 9999 | $\bigcirc$ |  |
| 251 | Output phase loss protection selection | 0， 1 | 1 | 251 | Output phase loss protection selection | 0， 1 | 1 | $\bigcirc$ |  |
| 252 | Override bias | 0 to 200\％ | 50\％ | 252 | Override bias | 0 to 200\％ | 50\％ | $\bigcirc$ |  |
| 253 | Override gain | 0 to 200\％ | 150\％ | 253 | Override gain | 0 to 200\％ | 150\％ | $\bigcirc$ |  |
| 255 | Life alarm status display | （0 to 15） | 0 | 255 | Life alarm status display | （0 to 31） | 0 | $\times$ | Also displayed in Pr． 255 in the FR－CC2． |
| 256 | Inrush current limit circuit life display | （0 to 100\％） | 100\％ | － | － | （03） | － | $\times$ | Displayed in Pr． 256 in the FR－CC2． |
| 257 | Control circuit capacitor life display | （0 to 100\％） | 100\％ | 257 | Control circuit capacitor life display | （0 to 100\％） | 100\％ | $\times$ | Also displayed in Pr． 257 in the FR－CC2． |
| 258 | Main circuit capacitor life display | （0 to 100\％） | 100\％ | － | － | － | － | $\times$ | Disabled． |
| 259 | Main circuit capacitor life measuring | 0，1 | 0 | － | － | － | － | $\times$ |  |
| 260 | PWM frequency automatic switchover | 0， 1 | 1 | 260 | PWM frequency automatic switchover | 0， 1 | 1 | $\bigcirc$ |  |


| FR-F700(P) parameter list |  |  |  | FR-F800 compatible parameter |  |  |  | Parameter setting |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Pr. | Name | Setting range | Initial value | Pr. | Name | Setting range | Initial value | Setting | Remarks |
| 261 | Power failure stop selection | 0, 1, 2, 21, 22 | 0 | 261 | Power failure stop selection | 0, 1, 2, 11, 12, 21, 22 | 0 | $\Delta$ | Setting Pr. 261 is required also in the FR-CC2 manufactured in August 2014 or later. Changing Pr. 21 after setting Pr. 264 and Pr. 265 will change the set values. |
| 262 | Subtracted frequency at deceleration start | 0 to 20 Hz | 3 Hz | 262 | Subtracted frequency at deceleration start | 0 to 20 Hz | 3 Hz | $\Delta$ |  |
| 263 | Subtraction starting frequency | 0 to $400 \mathrm{~Hz}, 9999$ | 60 Hz | 263 | Subtraction starting frequency | 0 to $590 \mathrm{~Hz}, 9999$ | 60 Hz | $\Delta$ |  |
| 264 | Power-failure deceleration time 1 | 0 to $3600 / 0$ to 360 s | 5 s | 264 | Power-failure deceleration time 1 | 0 to 3600 s | 5 s | $\Delta$ |  |
| 265 | Power-failure deceleration time 2 | 0 to $3600,9999 /$ 0 to 360 s, 9999 | 9999 | 265 | Power-failure deceleration time 2 | 0 to 3600, 9999 | 9999 | $\Delta$ |  |
| 266 | Power failure deceleration time switchover frequency | 0 to 400 Hz | 60 Hz | 266 | Power failure deceleration time switchover frequency | 0 to 590 Hz | 60 Hz | $\Delta$ |  |
| 267 | Terminal 4 input selection | 0, 1, 2 | 0 | 267 | Terminal 4 input selection | 0, 1, 2 | 0 | $\bigcirc$ |  |
| 268 | Monitor decimal digits selection | 0, 1,9999 | 9999 | 268 | Monitor decimal digits selection | 0, 1,9999 | 9999 | $\bigcirc$ |  |
|  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |
| 296 | Password lock level | $\begin{gathered} \hline 0 \text { to } 6,99,100 \text { to } 106,199, \\ 9999 \\ \hline \end{gathered}$ | 9999 | 296 | Password lock level | $\begin{gathered} 0 \text { to } 6,99,100 \text { to } 106,199, \\ 9999 \\ \hline \end{gathered}$ | 9999 | $\bigcirc$ |  |
| 297 | Password lock/unlock | (0 to 5), 1000 to 9998, 9999 | 9999 | 297 | Password lock/unlock | (0 to 5), 1000 to 9998,9999 | 9999 | $\times$ | Set the parameter as required. |
| 299 | Rotation direction detection selection at restart | 0, 1,9999 | 9999 | 299 | Rotation direction detection selection at restart | 0, 1,9999 | 9999 | $\bigcirc$ |  |
| 331 | RS-485 communication station number | 0 to 31 (0 to 247) | 0 | 331 | RS-485 communication station number | 0 to 31 (0 to 247) | 0 | $\bigcirc$ |  |
| 332 | RS-485 communication speed | 3, 6, 12, 24, 48, 96, 192, 384 | 96 | 332 | RS-485 communication speed | $\begin{gathered} 3,6,12,24,48,96,192,384, \\ 576,768,1152 \\ \hline \end{gathered}$ | 96 | $\bigcirc$ |  |
| 333 | RS-485 communication stop bit length | 0, 1, 10, 11 | 1 | 333 | RS-485 communication stop bit length / data length | 0, 1, 10, 11 | 1 | $\bigcirc$ |  |
| 334 | RS-485 communication parity check selection | 0,1,2 | 2 | 334 | RS-485 communication parity check selection | 0,1,2 | 2 | $\bigcirc$ |  |
| 335 | RS-485 communication retry count | 0 to 10, 9999 | 1 | 335 | RS-485 communication retry count | 0 to 10, 9999 | 1 | $\bigcirc$ |  |
| 336 | RS-485 communication check time interval | $0,0.1$ to $999.8 \mathrm{~s}, 9999$ | 0 s | 336 | RS-485 communication check time interval | 0 to $999.8 \mathrm{~s}, 9999$ | 0 s | $\bigcirc$ |  |
| 337 | RS-485 communication waiting time setting | 0 to $150 \mathrm{~ms}, 9999$ | 9999 | 337 | RS-485 communication waiting time setting | 0 to $150 \mathrm{~ms}, 9999$ | 9999 | $\bigcirc$ |  |
| 338 | Communication operation command source | 0, 1 | 0 | 338 | Communication operation command source | 0, 1 | 0 | $\bigcirc$ |  |
| 339 | Communication speed command source | 0, 1, 2 | 0 | 339 | Communication speed command source | 0, 1, 2 | 0 | $\bigcirc$ |  |
| 340 | Communication startup mode selection | 0, 1, 2, 10, 12 | 0 | 340 | Communication startup mode selection | 0, 1, 2, 10, 12 | 0 | $\bigcirc$ |  |
| 341 | RS-485 communication CR/LF selection | 0, 1,2 | 1 | 341 | RS-485 communication CR/LF selection | 0, 1, 2 | 1 | $\bigcirc$ |  |
| 342 | Communication EEPROM write selection | 0, 1 | 0 | 342 | Communication EEPROM write selection | 0, 1 | 0 | $\bigcirc$ |  |
| 343 | Communication error count | - | 0 | 343 | Communication error count | - | 0 | $\times$ | Setting not required |
| 374 | Overspeed detection level | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 374 | Overspeed detection level | 0 to 590 Hz | 9999 | $\bigcirc$ |  |
| 495 | Remote output selection | 0, 1, 10, 11 | 0 | 495 | Remote output selection | 0, 1, 10, 11 | 0 | $\bigcirc$ |  |
| 496 | Remote output data 1 | 0 to 4095 | 0 | 496 | Remote output data 1 | 0 to 4095 | 0 | $\bigcirc$ |  |
| 497 | Remote output data 2 | 0 to 4095 | 0 | 497 | Remote output data 2 | 0 to 4095 | 0 | $\bigcirc$ |  |
| 502 | Stop mode selection at communication error | 0 to 3 | 0 | 502 | Stop mode selection at communication error | 0 to 3 | 0 | $\bigcirc$ |  |
| 503 | Maintenance timer | 0 (1 to 9998) | 0 | 503 | Maintenance timer 1 | 0 (1 to 9998) | 0 | $\times$ | Setting not required |
| 504 | Maintenance timer alarm output set time | 0 to 9998, 9999 | 9999 | 504 | Maintenance timer 1 warning output set time | 0 to 9998, 9999 | 9999 | $\bigcirc$ |  |
| 505 | Speed setting reference | 1 to 120 Hz | 60 Hz | 505 | Speed setting reference | 1 to 590 Hz | 60 Hz | $\bigcirc$ |  |
| 522 | Output stop frequency | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 522 | Output stop frequency | 0 to $590 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 539 | Modbus-RTU communication check time interval | 0, 0.1 to $999.8 \mathrm{~s}, 9999$ | 9999 | 539 | Modbus-RTU communication check time interval | 0 to $999.8 \mathrm{~s}, 9999$ | 9999 | $\bigcirc$ |  |


| FR-F700(P) parameter list |  |  |  | FR-F800 compatible parameter |  |  |  | Parameter setting |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Pr. | Name | Setting range | Initial value | Pr. | Name | Setting range | Initial value | Setting | Remarks |
| 549 | Protocol selection | 0, 1 | 0 | 549 | Protocol selection | 0, 1, 2 | 0 | $\bigcirc$ |  |
| 550 | NET mode operation command source selection | 0, 1,9999 | 9999 | 550 | NET mode operation command source selection | 0, 1,9999 | 9999 | $\bigcirc$ |  |
| 551 | PU mode operation command source selection | 1,2 | 2 | 551 | PU mode operation command source selection | 1, 2, 3, 9999 | 9999 | $\bigcirc$ |  |
| 552 | Frequency jump range | 0 to $30 \mathrm{~Hz}, 9999$ | 9999 | 552 | Frequency jump range | 0 to $30 \mathrm{~Hz}, 9999$ | 9999 | $\bigcirc$ |  |
| 553 | PID deviation limit | 0 to 100.0\%, 9999 | 9999 | 553 | PID deviation limit | 0 to 100.0\%, 9999 | 9999 | $\bigcirc$ |  |
| 554 | PID signal operation selection | 0 to 3,10 to 13 | 0 | 554 | PID signal operation selection | 0 to 3, 10 to 13 | 0 | $\bigcirc$ |  |
| 555 | Current average time | 0.1 to 1.0 s | 1 s | 555 | Current average time | 0.1 to 1.0 s | 1 s | $\bigcirc$ |  |
| 556 | Data output mask time | 0.0 to 20.0 s | 0 s | 556 | Data output mask time | 0.0 to 20.0 s | 0 s | $\bigcirc$ |  |
| 557 | Current average value monitor signal output reference current | 0 to 3600 A | Inverter rated current | 557 | Current average value monitor signal output reference current | 0 to 3600 A | Inverter rated current | $\bigcirc$ |  |
| 563 | Energization time carrying-over times | ((0 to 65535)) | 0 | 563 | Energization time carrying-over times | ((0 to 65535)) | 0 | $\times$ | Setting not required |
| 564 | Operating time carrying-over times | ((0 to 65535)) | 0 | 564 | Operating time carrying-over times | ((0 to 65535)) | 0 | $\times$ | Setting not required |
| 571 | Holding time at a start | 0.0 to $10.0 \mathrm{~s}, 9999$ | 9999 | 571 | Holding time at a start | 0.0 to $10.0 \mathrm{~s}, 9999$ | 9999 | $\bigcirc$ |  |
| 575 | Output interruption detection time | 0 to 3600 s, 9999 | 1 s | 575 | Output interruption detection time | 0 to $3600 \mathrm{~s}, 9999$ | 1 s | $\bigcirc$ |  |
| 576 | Output interruption detection level | 0 to 400 Hz | 0 Hz | 576 | Output interruption detection level | 0 to 590 Hz | 0 Hz | $\bigcirc$ |  |
| 577 | Output interruption cancel level | 900 to 1100\% | 1000\% | 577 | Output interruption cancel level | 900 to 1100\% | 1000\% | $\bigcirc$ |  |
| 611 | Acceleration time at a restart | 0 to $3600 \mathrm{~s}, 9999$ | 15 s | 611 | Acceleration time at a restart | 0 to $3600 \mathrm{~s}, 9999$ | 9999 | $\bigcirc$ |  |
| 653 | Speed smoothing control | 0 to 200\% | 0\% | 653 | Speed smoothing control | 0 to 200\% | 0\% | $\bigcirc$ |  |
| 654 | Speed smoothing cutoff frequency | 0 to 120 Hz | 20 Hz | 654 | Speed smoothing cutoff frequency | 0 to 120 Hz | 20 Hz | $\bigcirc$ |  |
| 665 | Regeneration avoidance frequency gain | 0 to 200\% | 100\% | 665 | Regeneration avoidance frequency gain | 0 to 200\% | 100\% | $\bigcirc$ |  |
|  |  |  |  |  |  |  |  |  |  |
| 779 | Operation frequency during communication error | 0 to $400 \mathrm{~Hz}, 9999$ | 9999 | 779 | Operation frequency during communication error | 0 to 590 Hz , 9999 | 9999 | $\bigcirc$ |  |
| 791 | Acceleration time in low-speed range | 0 to $3600 / 360$ s, 9999 | 9999 | 791 | Acceleration time in low-speed range | 0 to 3600 / 360 s, 9999 | 9999 | $\bigcirc$ | Changing Pr. 21 after setting this parameter will change the set value. |
| 792 | Deceleration time in low-speed range | 0 to 3600 / 360 s, 9999 | 9999 | 792 | Deceleration time in low-speed range | 0 to 3600 / 360 s , 9999 | 9999 | $\bigcirc$ | Changing Pr. 21 after setting this parameter will change the set value. |
| 799 | Pulse increment setting for output power | $0.1 \mathrm{kWh}, 1 \mathrm{kWh}, 10 \mathrm{kWh}$, $100 \mathrm{kWh}, 1000 \mathrm{kWh}$ | 1 kWh | 799 | Pulse increment setting for output power | 0.1 kWh, 1 kWh, 10 kWh, $100 \mathrm{kWh}, 1000 \mathrm{kWh}$ | 1 kWh | $\bigcirc$ |  |
| 800 | Control method selection | 9, 20 | 20 | 800 | Control method selection | 9,20 | 20 | $\bigcirc$ |  |
| 820 | Speed control P gain 1 | 0 to 1000\% | 25\% | 820 | Speed control P gain 1 | 0 to 1000\% | 25\% | $\bigcirc$ |  |
| 821 | Speed control integral time 1 | 0 to 20 s | 0.333 s | 821 | Speed control integral time 1 | 0 to 20 s | 0.333 s | $\bigcirc$ |  |
| 867 | AM output filter | 0 to 5 s | 0.01 s | 867 | AM output filter | 0 to 5s | 0.01 s | $\bigcirc$ |  |
| 870 | Speed detection hysteresis | 0 to 5 Hz | 0 Hz | 870 | Speed detection hysteresis | 0 to 5 Hz | 0 Hz | $\bigcirc$ |  |
| 872 | Input phase loss protection selection | 0, 1 | 0 | - | - | - | - | $\times$ | Set Pr. 872 of the FR-CC2 to match the setting of the FR-F700(P). |
| 882 | Regeneration avoidance operation selection | 0, 1, 2 | 0 | 882 | Regeneration avoidance operation selection | 0, 1, 2 | 0 | $\bigcirc$ |  |
| 883 | Regeneration avoidance operation level | 300 to 800 V | $\begin{aligned} & 380 \mathrm{VDC/} \\ & 760 \text { VDC } \end{aligned}$ | 883 | Regeneration avoidance operation level | 300 to 800 V | $\begin{aligned} & 380 \mathrm{VDC/} \\ & 760 \mathrm{VDC} \end{aligned}$ | $\bigcirc$ |  |
| 884 | Regeneration avoidance at deceleration detection sensitivity | 0 to 5 | 0 | 884 | Regeneration avoidance at deceleration detection sensitivity | 0 to 5 | 0 | $\bigcirc$ |  |



| FR－F700（P）parameter list |  |  |  | FR－F800 compatible parameter |  |  |  | Parameter setting |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Pr． | Name | Setting range | Initial value | Pr． | Name | Setting range | Initial value | Setting | Remarks |
| 997 | Fault initiation | 16 to 18,32 to $34,48,49,64,80$ to $82,96,97,112,128,129,144$ ， 145，160，161， 176 to 179， 192 to 194， 196 to 199，208，230，241， 245 to $247,253,9999$ | 9999 | 997 | Fault initiation | 0 to 255， 9999 | 9999 | $\times$ | Setting not required |
| 998 | IPM parameter initialization | $\begin{gathered} 0,1,12,22,32,101,112,122, \\ 132 \end{gathered}$ | 0 | 998 | PM parameter initialization | $\begin{gathered} 0,12,112,8009,8109 \\ 9009,9109 \end{gathered}$ | 0 | $\times$ | Setting not required |
| 999 | Automatic parameter setting | 10，11，20，21，30，31， 9999 | 9999 | 999 | Automatic parameter setting | $\begin{gathered} 1,2,10,11,12,13,20,21, \\ 9999 \end{gathered}$ | 9999 | $\times$ | Setting not required |

## 4. 2. Restrictions for the FR-F800 Series

The following describes the restrictions on the replacement of the FR-F700(P) series with the FR-F800 series.
(1) Unsupported functions

| No. | Item | Remarks |
| :---: | :--- | :--- |
| 1 | Power failure stop <br> function | This function is available for the FR-CC2 manufactured in August <br> 2014 or later. |
| 2 | Special regenerative <br> brake duty |  |
| 3 | Main circuit capacitor <br> life display and life <br> check |  |
| 4 | Electronic bypass <br> sequence | When an error occurs in the FR-CC2, the commercial power supply <br> operation is not activated. <br> For the FR-CC2 manufactured in August 2014 or later, use the X95 <br> and X96 signals. |
| 5 | DC feeding mode | The FR-F842 does not support DC feeding mode 2. |
| 6 | Wamings and <br> protective functions | The FR-F842 does not support the brake transistor alarm detection <br> (E.BE). |

(2) Functions unsupported by the FR-F842 but supported by the FR-CC2 For the setting method, refer to the remarks in the parameter list.

| No. | Item | Remarks |
| :---: | :--- | :--- |
| 1 | Inrush current limit <br> circuit life check | This function can be set with the FR-CC2. |
| 2 | Wamings and <br> protective functions | With this function, the FR-CC2 can detect the instantaneous power <br> failure (E.IPF), undervoltage (E.UVT), input phase loss (E.ILF), and <br> inrush current limit circuit fault (E.IOH). |

(3) Other restrictions

| No. | Item | Remarks |
| :---: | :--- | :--- |
| 1 | USB (applicable to the <br> FR-CC2 only) | The FR-CC2 does not support the USB connector. |
| 2 | Startup time | If the power to the main circuit of the FR-CC2 is turned ON with the <br> control circuit power already ON, the FR-CC2 performs a reset. The <br> inverter is reset and the startup delays. |
| 3 | Operation panel <br> (applicable to the <br> FR-CC2 only) | Install the operation panel of the FR-A842 to set the FR-CC2. |

## 4. 3. PTC Thermistor Input

When a PTC thermistor is connected between terminals AU and SD with the AU/PTC switch set to PTC for the FR-F700(P), connect the thermistor between terminals 10 and 2 for the FR-F842.
For the FR-F842, set Pr. 561 (PTC thermistor protection level) and Pr. 1016 (PTC thermistor protection detection time).

## 4. 4. Compatibility of the Terminal Response Speed

The response of the input/output terminals of the FR-F800 is improved compared to the FR-F700(P). Operation timing of the device may differ depending on the usage.
In this case, set Pr. 289 (Inverter output terminal filter) and Pr. 699 (Input terminal filter) to adjust the terminal response time.
Set 5 to 8 ms in Pr. 289 and Pr. 699 and adjust according to the system.

## 5. OPTION

### 5.1. Option

The following table shows which FR-F700(P) series options are compatible with the FR-F800 series inverters and their corresponding FR-F800 series options.

| Name |  | Option model |  |
| :---: | :---: | :---: | :---: |
|  |  | FR-F700(P) | FR-F800 |
|  | 16-bit digital input | FR-A7AX | FR-A8AX |
|  | Digital output, additional analog output | FR-A7AY | FR-A8AY |
|  | Relay output | FR-A7AR | FR-A8AR |
|  | Profibus-DP | FR-A7NP | FR-A8NP |
|  | Device Net | FR-A7ND | FR-A8ND |
|  | CC-Link | FR-A7NC | FR-A8NC |
|  | CC-Link IE Field | FR-A7NCE | FR-A8NCE |
|  | Parameter unit | FR-PU07 | Some function restricted (parameter copy, operable parameters, etc.) <br> The battery mode of the FR-PU07BB is not available for the FR-CC2. |
|  | Parameter unit connection cable | FR-CB201,203,205 | Compatible |
|  | Power factor improving AC reactor | MT-BAL-H | Compatible. <br> If replacing the reactor, use FR-HAL-H. |
|  | Radio noise filter | FR-BIF-H | Compatible |
|  | Line noise filter | FR-BLF | Compatible |
|  | Brake unit | FR-BU-H, FR-BU2-H | Compatible. <br> The MT-BU5 is not compatible. |
|  | Resistor unit | MT-BR5-H | Compatible |
|  | FR-HC type high power factor converter | FR-HC2-H | Compatible. <br> In this case, FR-CC2 is not required. |
|  | Manual controller | FR-AX | Compatible |
|  | DC tach. follower | FR-AL | Compatible |
|  | Three speed selector | FR-AT | Compatible |
|  | Remote speed setter | FR-FK | Compatible |
|  | Ratio setter | FR-FH | Compatible |
|  | Speed detector | FR-FP | Compatible |
|  | Master controller | FR-FG | Compatible |
|  | Soft starter | FR-FC | Compatible |
|  | Deviation detector | FR-FD | Compatible |
|  | Preamplifier | FR-FA | Compatible |
| $\begin{aligned} & \frac{\varrho}{0} \\ & \pm \end{aligned}$ | Pilot generator | QVAH-10 | Compatible |
|  | Deviation sensor | YVGC-500W-NS | Compatible |
|  | Frequency setting potentiometer | WA2W 1k | Compatible |
|  | Analog frequency meter | YM206NRI 1mA | Compatible |
|  | Calibration resistor | RV24YN 10k $\Omega$ | Compatible |

## 5. 2. Replacement When the FR-A7NC Is Used

The FR-A7NC (CC-Link communication option) used with the FR-F700(P) series cannot be used with the FR-F800 series. For the CC-Link communication with the FR-F800 series, use the FR-A8NC.
(1) Shape and installation method

The following table shows the differences in the shape and installation method.

| Item | FR-A7NC | FR-A8NC | Remarks |
| :--- | :--- | :--- | :--- |
| Shape | Inverter plug-in option type, <br> terminal block connection | Inverter plug-in option type, <br> terminal block connection | Although the connection method is <br> the same, the circuit board of the <br> option has a different shape. |
| Connection terminal block | Dedicated terminal block <br> (M2 small flathead screw) | A6CON-L5P <br> Insertion wiring | The shape of the terminal block and <br> wiring method differ. A terminal block <br> is not enclosed. |
| Installation procedure | Connected to the option <br> connector 3. <br> *After wiring the terminal <br> block, install the front cover. | Connected to the option <br> connector 1. <br> * After wiring the terminal <br> block, install the front cover. |  |
| Terminating resistor | Terminating resistor <br> selection switch | Terminating resistor <br> selection switch |  |
| Connection cable | CC-Link dedicated cable | CC-Link dedicated cable |  |

[Shape of the FR-A7NC]
$\begin{aligned} & \text { Connector for } \\ & \text { communication } \\ & \text { Mount the } \\ & \text { accessory } \\ & \text { terminal block to } \\ & \text { connect to the } \\ & \text { network. }\end{aligned}$
$\begin{aligned} & \text { Mounting } \\ & \text { hole }\end{aligned}$
Select the resistor value of the terminating resistor.
Front View
Operation status indication LED
Lit/flicker of the LED indicate operation status.
[Shape of the FR-A8NC]


| Symbol | Name | Description |
| :---: | :--- | :--- |
| a | Mounting hole | Used to fix the option to the inverter by inserting a mounting screw <br> or a spacer. |
| b | CC-Link communication one-touch connector | CC-Link communication can be performed with the CC-Link <br> communication connector. |
| c | Switch for manufacturer setting | Switch for manufacturer setting. Do not change the initial setting <br> (OFF). |
| d | Terminating resistor selection switch | Select the resistor value of the terminating resistor. |
| e | Connector | Connected to the option connector of the inverter. |

## [Installation procedure of the FR-A8NC]

## - Installation of the communication option LED display cover

(1) Remove the inverter front cover. (Refer to Chapter 2 of the Instruction Manual (Detailed) of the inverter for details on how to remove the front cover.)
Mount the cover for displaying the operation status indication LED for the communication option on the inverter front cover.
(2) Cut off hooks on the rear of the inverter front cover with nipper, etc. and open a window for fitting the LED display cover
(3) Fit the communication option LED display cover to the front of the inverter front cover and push it into until fixed with hooks.


## NOTE

- The protective structure (JEM1030) changes to the open type (IP00).


## - Installing the option

(1) For the two mounting holes (as shown in the next page) that will not be tightened with mounting screws, insert spacers.
(2) Fit the connector of the plug-in option to the guide of the connector on the inverter unit side, and insert the plug-in option as far as it goes. (Insert it to the inverter option connector 1.)
(3) Fit the one location on the left of the earth plate (as shown in the next page) securely to the inverter unit by screwing in the supplied mounting screw. (tightening torque 0.33 $\mathrm{N} \cdot \mathrm{m}$ to $0.40 \mathrm{~N} \cdot \mathrm{~m}$ )
(4) Fit the one location on the left of the plug-in option securely to the inverter unit and the right of the plug-in option to the inverter unit together with the earth plate by screwing in the supplied mounting screws. (tightening torque $0.33 \mathrm{~N} \cdot \mathrm{~m}$ to $0.40 \mathrm{~N} \cdot \mathrm{~m}$ ) If the screw holes do not line up, the connector may not be inserted deep enough
 Check the connector.


Insertion positions for screws and spacers

## [Connection cable of the FR-A8NC]

In the CC-Link system, use CC-Link dedicated cables.
If the cable used is other than the CC-Link dedicated cable, the performance of the CC-Link system is not guaranteed.
For the specifications of the CC-Link dedicated cable, refer to the website of the CC-Link Partner Association.

- Website of the CC-Link Partner Association http://www.cc-link.org/
- One-touch communication connector plug (as of July 2013)

Refer to the following table for the plug required to fabricate a cable on your own

| Model | Manufacturer |
| :--- | :--- |
| A6CON-L5P | Mitsubishi Electric Corporation |
| $35505-6000-$ BOM GF | Sumitomo 3M Limited |

(1) Cable-end treatment

Apply the following treatment to the CC-Link dedicated cable that is inserted to a one-touch communication connector plug.


## ©…NOTE

- Where possible, round the cable tip that is cut off with a tool such as nippers. If the cable is not rounded, it may get caught in the middle of a plug, without fully entering into the plug.
- If required, apply an insulation treatment to the shielding wire area where it is not covered by the one-touch communication connector plug.
(2) Plug cover check

Check that a plug cover is snapped into a plug


- Do not push the plug cover onto the plug before inserting a cable. Once crimped, the plug cover cannot be reused
(3) Cable insertion

Lift up the tail of the plug cover, and fully insert a cable. Insert different signal wires to the one-touch communication connector plug as shown in the right figure.


## O- NOTE:

- Insert the cable fully. Failure to do so may cause a crimping failure
- A cable sometimes comes out of the head of the cover. In that case, pull the cable a little so that the cable stays under the plug cover.
(4) Crimping the plug cover

Push the plug cover onto the plug with a tool such as pliers. After crimping, check that the plug cover is securely snapped into the plug as shown in the right figure.

## :-NOTE:

- Misaligned latches between the plug cover and the plug may keep the cover lifted. The plug cover is not sufficiently crimped in this condition. Push the plug cover until it snaps into the plug

Connect the CC-Link dedicated cable to the CC-Link communication connector.


- When wiring cables to the inverter's RS-485 terminals while a plug-in option is mounted, take caution not to let the cables touch the circuit board of the option or of the inverter. Otherwise, electromagnetic noises may cause malfunctions.
[Setting of the terminating resistor selection switch of the FR-A8NC]
For the inverter (FR-A8NC) of the end station, configure the terminating resistor selection switch setting in advance.
The following table shows the specifications of the terminating resistor selection switch.
Configure the same setting as the terminating resistor selection switch of the FR-A7NC.

| Setting | 1 | 2 | Description |
| :---: | :---: | :---: | :---: |
| ${ }_{2 \sim}^{1 \sim}{ }^{1}$ | OFF | OFF | Without terminating resistor (initial setting) |
| [ $\begin{aligned} & 1 \square 0 \\ & 2 \square\end{aligned}$ | ON | OFF | Do not use. |
| $1 \square^{1} \square^{0}$ | OFF | ON | $130 \Omega$ (resistance value with the CC-Link Ver. 1.00 dedicated high performance cable) |
| ${ }^{1+\square^{0}}$ | ON | ON | $110 \Omega$ |

The parameter numbers are the same．Refer to the following table to set the parameters．

## List of FR－A8NC parameters compatible with the FR－A7NC

The following table shows the parameter settings of the FR－F800 series inverter required when replacing an FR－A7NC by an FR－A8NC
When an FR－F700（P）series parameter is set to a value other than the initial value，set the corresponding FR－F800 parameter according to the following table
When an FR－F700（P）series parameter is set to an initial value，it is usually not necessary to change the corresponding FR－F800 parameter setting．
Setting ©：Set the FR－F700（P）parameter as it is．
$\Delta$ ：Change the FR－F700（P）parameter and set
$x$ ：Adjust or set the FR－F800 parameter．

| FR－F700（P）parameter list |  |  |  | FR－F800 compatible parameter |  |  |  | Parameter setting |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Pr． | Name | Setting range | Initial value | Pr． | Name | Setting range | Initial value | Setting | Remarks |
| 313 | DO0 output selection | $\begin{gathered} \hline 0 \text { to } 5,7,8,10 \text { to } 19, \\ 25,26,45 \text { to } 48,57, \\ 64,67,70,79,85 \text { to } \\ 96,89,99,100 \text { to } \\ 105,107,108,110 \\ \text { to } 119,125,126, \\ 145 \text { to } 148,157, \\ 164,167,170,179, \\ 185 \text { to } 196,198, \\ 199,9999 \\ \hline \end{gathered}$ | 9999 | 313 | DO0 output selection | 0 to $5,7,8,10$ to $19,25,26,35,39$ ， 40,45 to $54,57,64$ to 68,70 to 79 ， 82， 85 to 96,98 to $105,107,108$ ， 110 to $116,125,126,135,139,140$ ， 145 to $154,157,164$ to 168,170 to 179，182， 185 to 196， 198 to 208， 211 to $213,215,300$ to 308,311 to 313，315， 9999 | 9999 | $\bigcirc$ |  |
| 314 | DO1 output selection |  | 9999 | 314 | DO1 output selection |  | 9999 | $\bigcirc$ |  |
| 315 | DO2 output selection |  | 9999 | 315 | DO2 output selection |  | 9999 | $\bigcirc$ |  |
| 338 | Communication operation command source | 0， 1 | 0 | 338 | Communication operation command source | 0， 1 | 0 | $\bigcirc$ |  |
| 339 | Communication speed command source | 0，1， 2 | 0 | 339 | Communication speed command source | 0，1， 2 | 0 | $\bigcirc$ |  |
| 340 | Communication startup mode selection | 0，1，2，10， 12 | 0 | 340 | Communication startup mode selection | 0，1，2，10， 12 | 0 | $\bigcirc$ |  |
| 342 | Communication EEPROM write selection | 0， 1 | 0 | 342 | Communication EEPROM write selection | 0， 1 | 0 | $\bigcirc$ |  |
| 349 | Communication reset selection | 0， 1 | 0 | 349 | Communication reset selection | 0， 1 | 0 | $\bigcirc$ |  |
| 500 | Communication error execution waiting time | 0 to 999.8 s | 0 s | 500 | Communication error execution waiting time | 0 to 999.8 s | 0 s | $\bigcirc$ |  |
| 501 | Communication error occurrence count display | 0 | 0 | 501 | Communication error occurrence count display | 0 | 0 | $\bigcirc$ |  |
| 502 | Stop mode selection at communication error | 0 to 3 | 0 | 502 | Stop mode selection at communication error | 0 to 3 | 0 | $\bigcirc$ |  |
| 541 | Frequency command sign selection （CC－Link） | 0， 1 | 0 | 541 | Frequency command sign selection（CC－Link） | 0， 1 | 0 | $\bigcirc$ |  |
| 542 | $\begin{aligned} & \text { Communication station number } \\ & \text { (CC-Link) } \end{aligned}$ | 1 to 64 | 1 | 542 | Communication station number （CC－Link） | 1 to 64 | 1 | $\bigcirc$ |  |
| 543 | Baud rate selection（CC－Link） | 0 to 4 | 0 | 543 | Baud rate selection（CC－Link） | 0 to 4 | 0 | $\bigcirc$ |  |
| 544 | CC－Link extended setting | 0，1，12，14， 18 | 0 | 544 | CC－Link extended setting | $0,1,12,14,18,100,112,114,118$ | 0 | $\bigcirc$ |  |
| 550 | NET mode operation command source selection | 0，1，9999 | 9999 | 550 | NET mode operation command source selection | 0，1， 9999 | 9999 | $\bigcirc$ |  |


[^0]:    NOTE:

    - When using stranded wires without a blade terminal, twist enough to avoid short circuit with a nearby terminals or wires.
    - Place the flathead screwdriver vertical to the open/close button. In case the blade tip slips, it may cause an inverter damage or injury.

