

FACTORY AUTOMATION

MITSUBISHI ELECTRIC INDUSTRIAL ROBOT MELFA CR Series





Mitsubishi Electric Corporation operates across a wide range of sectors, from home appliances and building systems to railway solutions, factory automation equipment, and satellites and leverages the synergy created by these diverse sectors to address various challenges and provide optimal solutions worldwide.

We, the Mitsubishi Electric Group, will continue to evolve in "carbon neutrality" and a "circular economy" by promoting innovation in products and services and providing integrated solutions through our business activities, all in order to realize a vibrant and sustainable society.

Under "Changes for the Better" which reflects the Mitsubishi Electric Group's commitment to "always strive to achieve something better", Mitsubishi Electric FA will expand the value of its products and services in the FA system business by advancing the provision and expansion of integrated solutions under the slogan "Automating the World" for an even better tomorrow. Through automation technology, we aim to contribute to innovation not only in the manufacturing industry but also across society as a whole.

We stand as your partner in shaping a smarter, more efficient, and more sustainable future.

SUSTAINABLE DEVELOPMENT GOALS

The Mitsubishi Electric Group is actively solving social issues, such as decarbonization and labor shortages, by providing production sites with energy-saving equipment and solutions that utilize automation systems, thereby helping towards a sustainable society.

OVERVIEW

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System configuration	18
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2
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4
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6

Functions and options may be supported in certain versions or later.
For information on their availability, refer to the instruction manual for each function or option.



Compact & Stylish



Common & Simple



Convenient & Stress free



Increased customer satisfaction

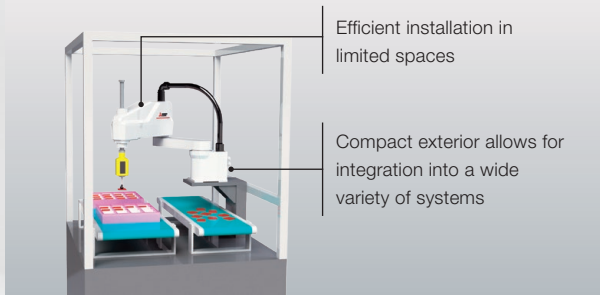
MELFA CR Series

Scan here for the MELFA CR series concept video



Compact exterior

Installable in limited spaces



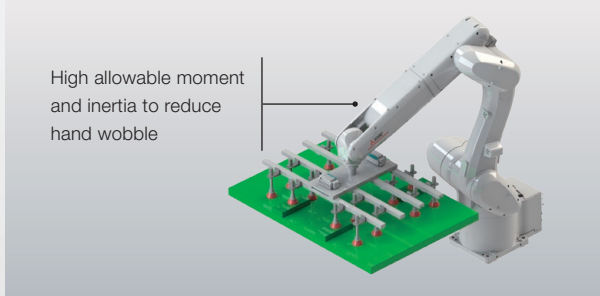
Stylish construction

Applications in various environments and processes



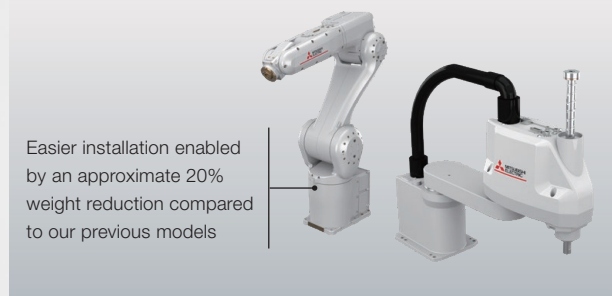
Specialized basic performance

Improved continuous operation



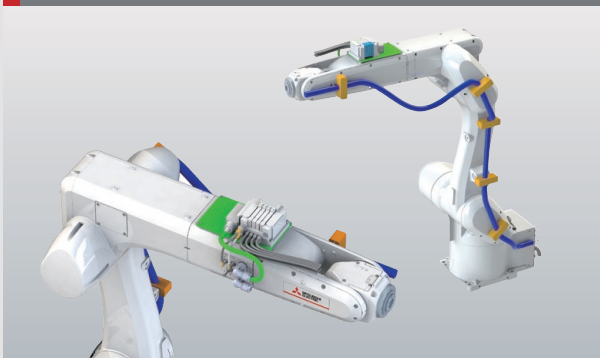
Simple design

Lightweight robot arm



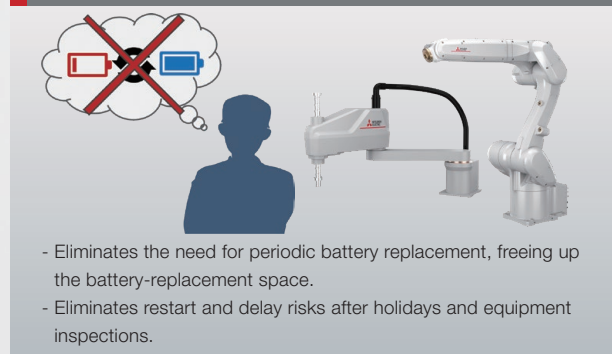
Convenient user interface

Internal wiring for reduced disconnection risk / Ample inputs and outputs



Stress-free management

Battery-less for improved maintainability (excluding the 3CRH and 6CRH)





Vertical articulated robot

RV-CR Series

- Slim arm and compact joints with a smooth and curved design
- Moment and inertia specifications for large hands
- Compliance for oil mist environments as standard (IP65), allowing for a variety of uses
- Battery-less for improved maintainability

RV-CR Series

Model		
	RV-8CRL	RV-12CRL
Max. payload	8 kg	12 kg
Reach	931 mm	1504 mm
Environment specifications	Oil mist (IP65)	

Model

RV-◇CRL-D

1 2 3 4 5 6

1 Robot structure

RV: Vertical articulated robot

2 Payload

8: 8 kg / 12: 12 kg

3 Series name

CR: CR Series

4 Arm length

L: Long arm

5 Controller type

D: Standalone

6 Special model number

None: 2D-TZ368 is pre-installed in the controller.

-S15: 2D-TZ378 is pre-installed in the controller.



Horizontal articulated robot

RH-CRH Series

- Reduced overall height for a compact design
- Reduced weight for improved continuous operation performance
- Multiple variations to fit various uses

RH-CRH Series

Model				
	RH-3CRH	RH-6CRH	RH-10CRH	RH-20CRH
Max. payload	3 kg	6 kg	10 kg	20 kg
Reach	400 mm	600 mm / 700 mm	600 mm / 700 mm / 800 mm	850 mm / 1000 mm
Z stroke	180 mm	200 mm	200 mm / 300 mm	420 mm
Environment specifications	Standard (IP20)			

Model

RH-◇CRH□□△△-D□

1 2 3 4 5 6 7

1 Robot structure

RH: Horizontal articulated robot

2 Payload

3: 3 kg / 6: 6 kg / 10: 10 kg / 20: 20 kg

3 Series name

CRH: CRH series

4 Arm length

40: 400 mm / 60: 600 mm
70: 700 mm / 80: 800 mm
85: 850 mm / 100: 1000 mm

5 Stroke length

18: 180 mm / 20: 200 mm
30: 300 mm / 42: 420 mm

6 Controller type

D: Standalone

7 Special model number

None: 2D-TZ368 is pre-installed in the controller.
-S15: 2D-TZ378 is pre-installed in the controller.

Slim & Compact Robot Offering a High Level of Utility and Design

RV

RH

Maximum performance in minimum space

Slim & compact

A smooth, curved design complements the slim arm and compact joints. The external design is marked by minimalist, functional design.

High scalability

The MELFA CR series supports a wide range of functions and options, including the tracking function (installed as standard), additional axis control (installed as standard), 2D vision sensor, force sensor, 3D vision sensor, and network base card, making it useful in various situations.



Lighter unit

Compared to the MELFA FR series, the MELFA CR series is lighter thanks to a simplified drive system and optimized arm structure. The lineup has also been expanded.

MELFA RV-CR series robots are easy to integrate with automation cells and manufacturing equipment, and their slim structure makes them easy to handle.

Improved maintainability

No backup battery

The use of a HK motor eliminates the need for a battery to back up the robot's internal encoder data.

This eliminates the cost and effort of regular replacement as well as the risk of losing origin data due to battery depletion (excluding the 3CRH and 6CRH).

Belt-less coaxial drive mechanism

For vertical articulated robots, coaxial drive mechanisms transfer power to the axes without belts. (J4/J5 axes on the RV-8CRL. Excluding the J5 axis on the RV-12CRL.)

Simplification of the structure has improved transmission efficiency and reliability. Maintainability has also been improved by reducing the number of points for periodic belt inspections.

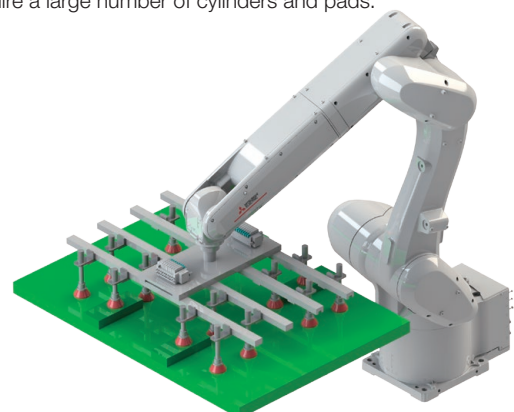
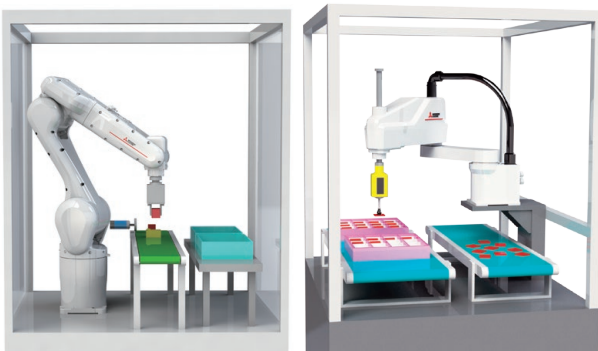
Protrusionless structure suppresses interference with surroundings

In addition to a slim, compact exterior and small robot base, the structures feature minimal protrusions on the front, back, and sides, reducing interference with surroundings during operation. Horizontal articulated robots have a slim arm and reduced overall height making them suited to integration with automation cells and manufacturing equipment.

Large grippers for various situations

RV-12CRL has a large moment / inertia and an extensive number of inputs / outputs for gripper control, which makes the installation of large and complex grippers possible.

This enables the stable transfer of large workpieces using grippers that require a large number of cylinders and pads.

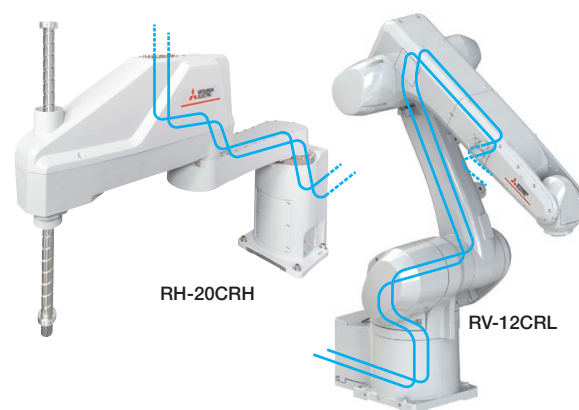


Wiring/piping built into arm

Signal wiring and air piping that can be used for gripper control, etc., are built in from the base to the forearm.

For the RV-8CRL series and RH-CRH series, both ends of the signal wire are equipped with universal D-sub connectors for use in various applications.

RV-12CRL has two 15-pin connectors at both ends of the signal wires to handle a large number of signals. Connectors and air joints are on the side, making it easy to route the wiring.



Built-in signal wiring and air piping for gripper control

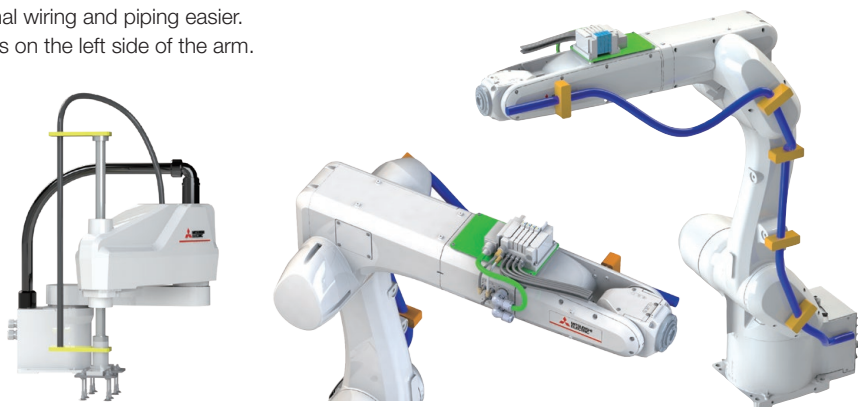
Structure supporting external wiring/piping

The CR series is designed to make external wiring and piping easier.

The RV-12CRL has numerous screw holes on the left side of the arm.

The internal wiring and piping are routed on the right side of the robot allowing for installation without interference.

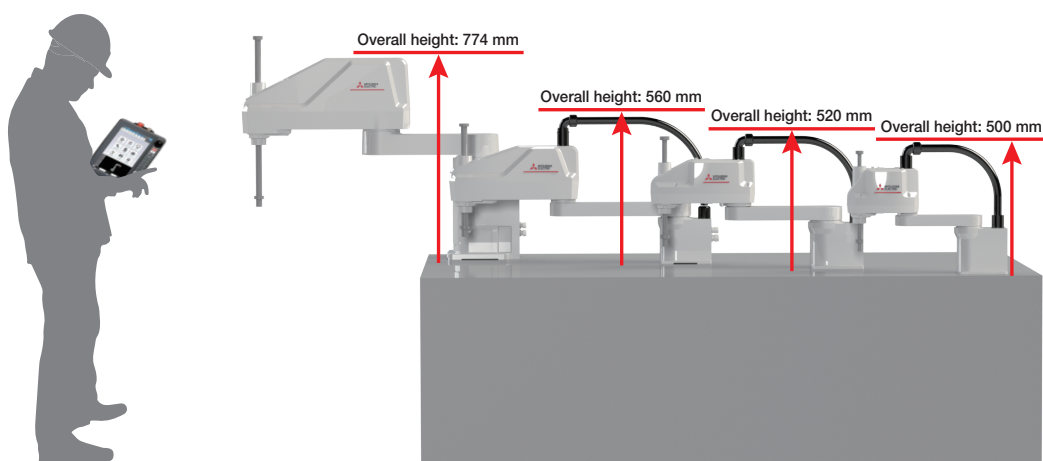
For the RH-CRH series, wiring can also be routed to follow the movement of the J3 and J4 axes.



Reduced overall height for a compact design

The overall height of the RH-CRH series has been reduced by making the arm cover compact.

The compact exterior enables the robot to be incorporated into a wide variety of systems.



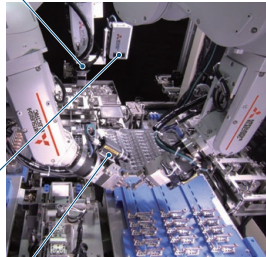
High-performance Controller Makes MELFA More Intelligent

Intelligent technology

Force sensor

- Checks pressing force and force conditions at time of insertion, improving operational quality
- Assembly of difficult-to-fit workpieces
- Teaching support via force information
- Improved force controllability via faster control cycle

Example use of intelligent technology



3D vision sensor

- Kitting and separation of scattered or stacked workpieces
- Simplification of installation via support functions

2D vision sensor

- Vision sensor configuration tool allows easy calibration of robot and camera
- Easy connection of robot and camera via Ethernet
- Easy control via robot program vision control command

Intelligent technology: MELFA Smart Plus

Advanced features such as integration functions for the various sensors and autonomous startup adjustment functions are provided for all phases of customer's operations, from design and startup through to operation and maintenance.

MELFA

Smart Plus

Preventive maintenance function

Tracking the robot's operating status helps manage the condition of the robot.

Coordinated control of additional axis

Links robot and travel base for high-accuracy processing and assembly at specific speed.

Robot mechanism thermal compensation function

Compensates the thermal expansion of the robot arm to increase position accuracy.

Calibration assistance function

● Automatic calibration

Automatically adjusts the coordinates of the vision sensor to increase position accuracy.

● Workpiece coordinate calibration

Adjusts the robot and workpiece coordinates using a vision sensor to increase position accuracy.

● Relative position calibration

Automatically calibrates the positions of multiple robots using a vision sensor. Increases position accuracy in collaborative operation.

2D vision sensor enhancement function

Various vision applications are easily set up.

Force sensor enhancement function

Parameters for the optimum operation pattern are found using repeat learning in a short amount of time.

MELFA-3D Vision enhancement function

Reduced startup time thanks to automatic parameter adjustments.

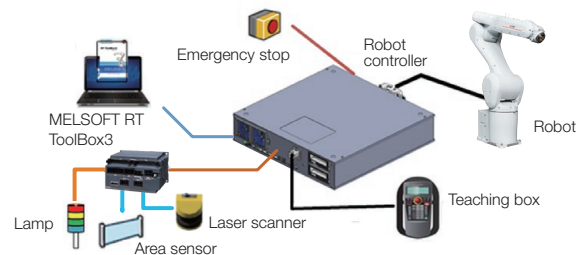
Safety functions

Safety monitoring function

A high level of safety that complies with international standards, allows for flexibility in building equipment.

Safety I/O

Extends redundant safety I/O to 8 inputs and 4 outputs. Enables development of various safety systems.



Safety logic editing

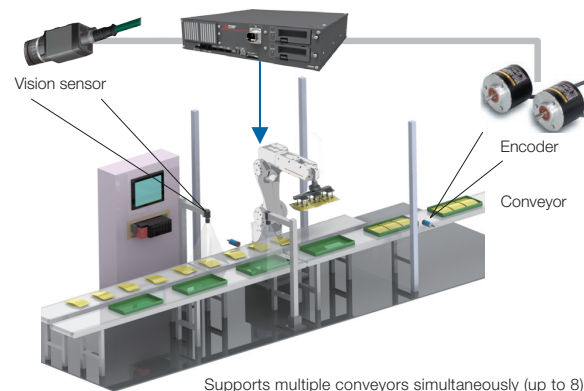
The operating conditions for the safety monitoring function can be easily defined from the setting screen.

Tracking and additional axis control

Comes standard with tracking and additional axis control

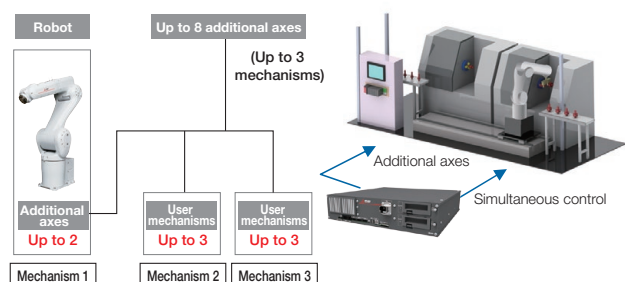
Tracking

Robot tracks workpiece on conveyor, allowing transfer, alignment, and assembly without stopping conveyor.



Additional axis control

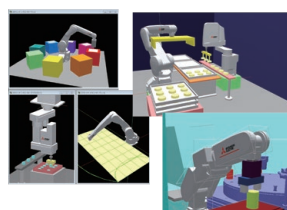
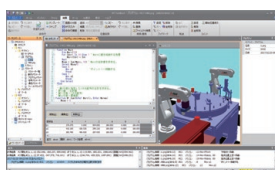
Build user mechanism controlling additional axes simultaneously with robot such as robot drive axis or turntable or separate from robot such as loader or positioning device. Control up to 8 axes. Our MELSERVO (MR-J5-B or MR-J4-B) servomotor can be used with additional axes.



Software supporting program creation and total engineering: MELSOFT RT ToolBox3

PC software supporting everything from robot system design to installation, debugging, operation, and maintenance

- Program editing and debugging
- Simulation function
- 3D viewer
- Monitoring function
- Melfa RXM.ocx communication middleware



Visual programming

The visual programming function creates programs simply by connecting blocks corresponding to each command.

Visual programming enables intuitive operation, which makes it easy to start up robots even without knowledge of robotics.

Supporting major networks

Supports various networks for system expansion

Compatible with an optional network base card that supports four major networks, enabling system configuration using devices from various manufacturers and communication with higher-level devices.

Network	Base card model
CC-Link IE TSN	2F-DQ535-TSN
CC-Link IE Field	2F-DQ535
EtherCAT	2F-DQ535-EC
EtherNet/IP	2F-DQ535-EIP
PROFINET IO	2F-DQ535-PN

Low-profile controller

Space-saving design

The CR800 controller is slim with a height of 99.5 mm and can be used in both vertical and horizontal positions. The controller can be placed in a variety of positions to fit into the available space of a device, contributing to space-saving.

Abundant inputs and outputs

Parallel I/O interface included as standard

For the CR series, the parallel I/O interface card is installed in the controller as standard. 32 inputs and 32 outputs can be externally inputted/outputted, which can be used for gripper control and peripheral equipment control.

Gripper cable options

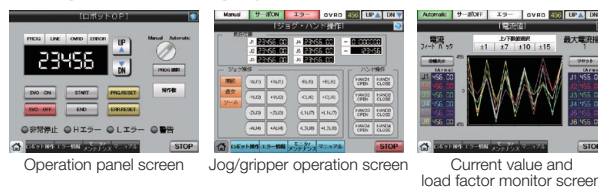
For RV-12CRL, gripper cable options are available. This provides easier signal management of the gripper and controller, and reduces installation work-hours.

GOT integration

Directly linked with GOT

Enhanced efficiency of monitoring and maintenance operations onsite using a single GOT (display device) as the Human Machine Interface (HMI).

Example of GOT display



Enables the robot to be controlled from the GOT even without a teaching box.

Current robot position data, error information, etc. can be displayed easily on the GOT.

Internal robot information

- Error, variable, and program information
- Robot status (Current speed, current position, etc.)
- Maintenance information (Remaining battery capacity, grease life, etc.)
- Servo data (Load factor, current values, etc.)

Sample image files can be downloaded from the Mitsubishi Electric FA website.

- Useful sample image files that can immediately be used in actual systems.
- Sample sequence programs (function blocks) are provided for using the sample image files.

Note) The sample image files are for the GT27 (640 × 480 or better). To use the files, GT Designer3 version 1.178L or later is required.

Product specifications

MELFA RV-8CRL

Vertical 8 kg Type

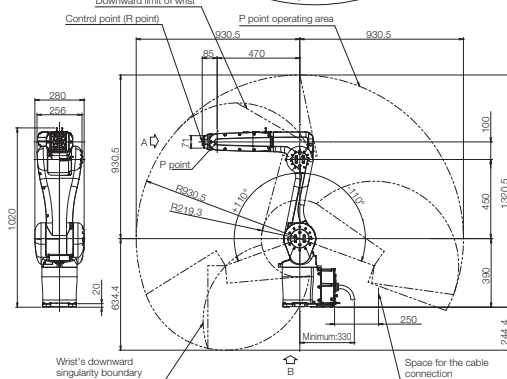
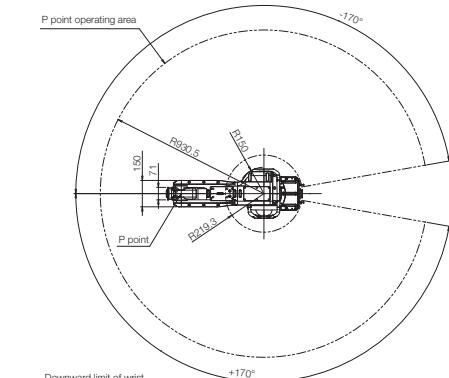
RV-8CRL



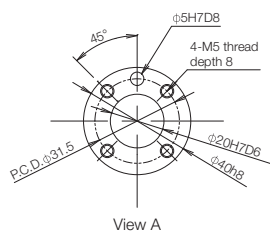
Specifications

Item	Unit	RV-8CRL
IP rating		IP65*1
Environment		Oil mist specification
Installation posture		On floor, hanging, (against wall*2)
Connected controller		CR800-CVD
Structure		Vertical articulated robot
Degree of freedom		6
Load	Rating	kg
	Maximum	kg
Max. reach (P point)	mm	931
Arm length	mm	450+470
Operating range	J1	Degree
	J2	Degree
	J3	Degree
	J4	Degree
	J5	Degree
	J6	Degree
Maximum speed*4	J1	Degree/s
	J2	Degree/s
	J3	Degree/s
	J4	Degree/s
	J5	Degree/s
	J6	Degree/s
Pose repeatability	mm	±0.02
Ambient temperature	°C	0 to 40
Allowable moment load	J4	Nm
	J5	Nm
	J6	Nm
Allowable inertia	J4	kgm ²
	J5	kgm ²
	J6	kgm ²
Mass	kg	41
Tool wiring		D-sub 15 pins
Tool pneumatic pipes		Φ6 × 2

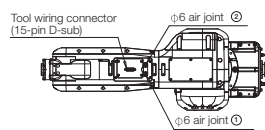
External dimensions/operating range



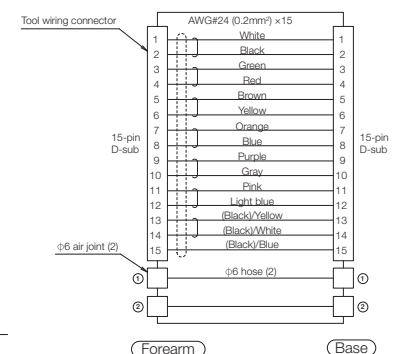
Mechanical interface



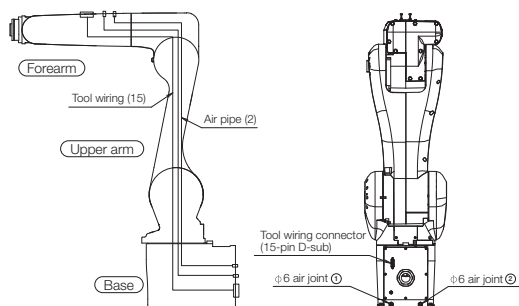
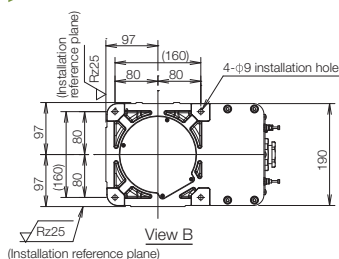
Internal wiring/piping



Wiring/piping



Installation dimensions



*1: Electrical devices and high-speed rotating parts susceptible to the effects of dust and water inside the arm are under the protection of IP65. Refer to the standard specifications manual for details.

*2: The wall mounting specifications are special specifications that restrict the operating range of the J1 axis.

*3: "Maximum load capacity" is the maximum weight that can be loaded under the limitation of a mechanical interface having a downward attitude (within ±10° of the vertical position).

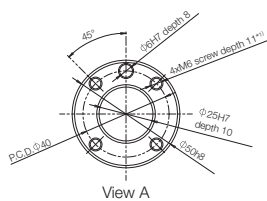
*4: The maximum speed indicates the peak value, and the speed of each axis varies depending on factors such as the posture, load, and the amount of movement.

Vertical 12 kg Type

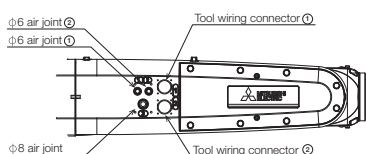
► Specifications

Item		Unit	RV-12CRL
IP rating			IP65*1
Environment			Oil mist specification
Installation posture			On floor, hanging
Connected controller			CR800-12CVD
Structure			Vertical articulated robot
Degree of freedom			6
Load	Rating	kg	12
	Maximum	kg	12
Max. reach (P point)		mm	1504
Arm length		mm	600+760
Operating range	J1	Degree	±170
	J2	Degree	-90 to +150
	J3	Degree	+0 to +170
	J4	Degree	±190
	J5	Degree	±120
	J6	Degree	±360
Maximum speed*2	J1	Degree/s	270
	J2	Degree/s	253
	J3	Degree/s	290
	J4	Degree/s	487
	J5	Degree/s	480
	J6	Degree/s	780
Pose repeatability		mm	±0.04
Ambient temperature		°C	0 to 40
Allowable moment load	J4	Nm	26.5
	J5	Nm	26.5
	J6	Nm	11
Allowable inertia	J4	kgm ²	0.9
	J5	kgm ²	0.9
	J6	kgm ²	0.3
Mass		kg	110
Tool wiring			2×15 pins
Tool pneumatic pipes			φ6 × 2, φ8 × 1

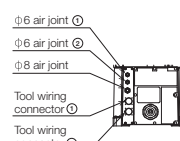
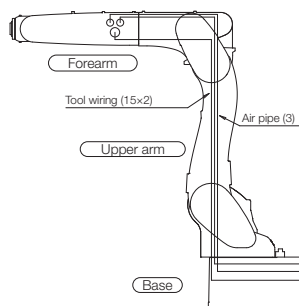
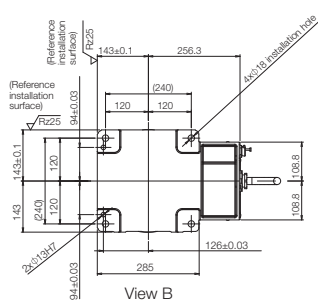
► Mechanical interface



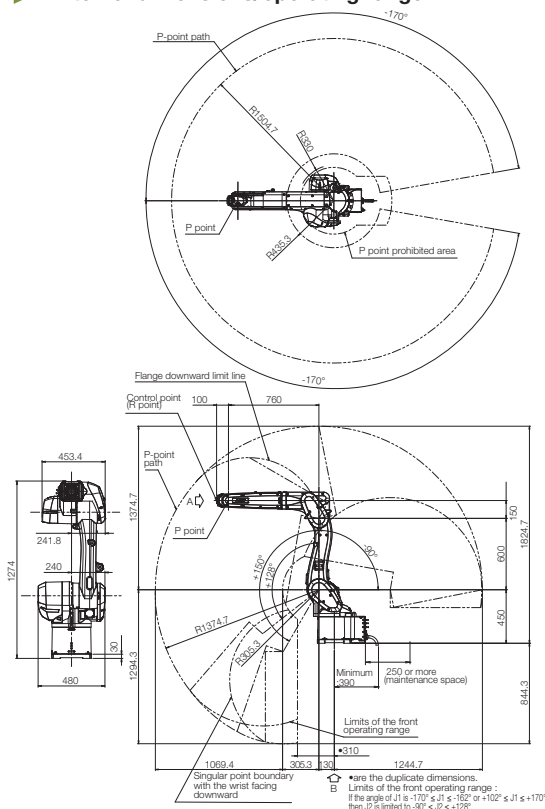
► **Internal wiring/piping**



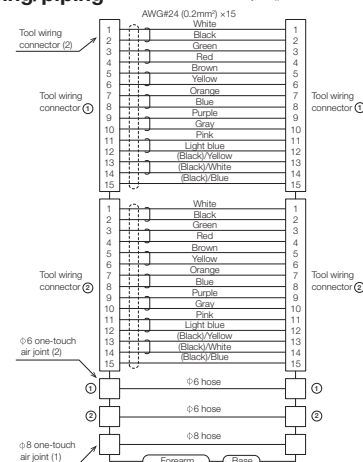
► Installation dimensions



► **External dimensions/operating range**



► **Wiring/piping**



*1: Electrical devices and high-speed rotating parts susceptible to the effects of dust and water inside the arm are under the protection of IP65. Refer to the standard specifications manual for details.

*2: The maximum speed indicates the peak value, and the speed of each axis varies depending on factors such as the posture, load, and the amount of movement.

MELFA RH-3CRH

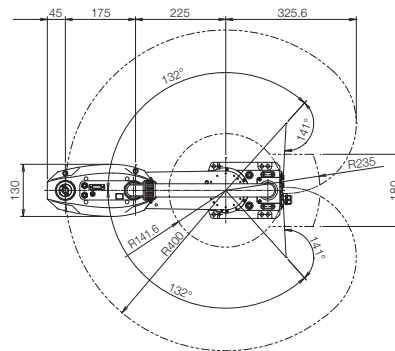
Horizontal 3 kg Type

Specifications

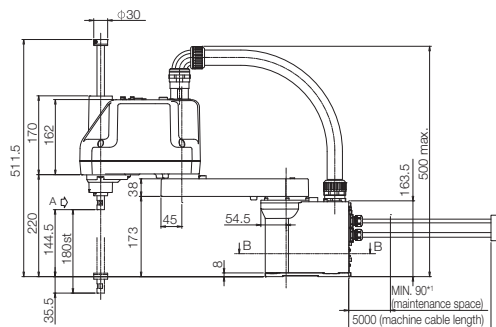
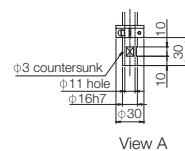
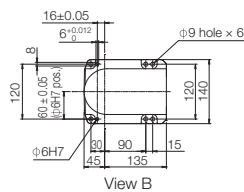
Item	Unit	RH-3CRH4018
IP rating		IP20
Environment		Standard
Installation posture		On floor
Connected controller		CR800-CHD
Structure		Horizontal articulated robot
Degree of freedom		4
Load	Rating	kg
	Maximum	kg
Max. reach (Arm No. 1 + Arm No. 2)	mm	400
Arm length	Arm No. 1	mm
	Arm No. 2	mm
Operating range	J1	Degree
	J2	Degree
	J3 (Z)	mm
	J4 (θ)	Degree
Maximum speed*1	J1	Degree/s
	J2	Degree/s
	J3	mm/s
	J4	Degree/s
	J1+J2	mm/s
Pose repeatability	X-Y composite	mm
	J3 (Z)	mm
	J4 (θ)	Degree
Ambient temperature	°C	0 to 40
Allowable inertia	Rating	kgm ²
	Maximum	kgm ²
Mass	kg	14
Tool wiring		15 points, D-SUB
Tool pneumatic pipes		Φ6 × 2, Φ4 × 1
Brake		J1, J2, J4 axes (without brake) J3 axis (with brake)



Operating range



External dimensions



*1: This is the space required for battery replacement, and indicates the dimensions including the minimum bending radius of the machine cable.

*1: The values are taken when the robot is in MvTune2 (high-speed operation mode). Additionally, the values are taken under load conditions where no effect comes from automatic speed compensation due to the load mass.

MELFA RH-6CRH

Horizontal 6 kg Type

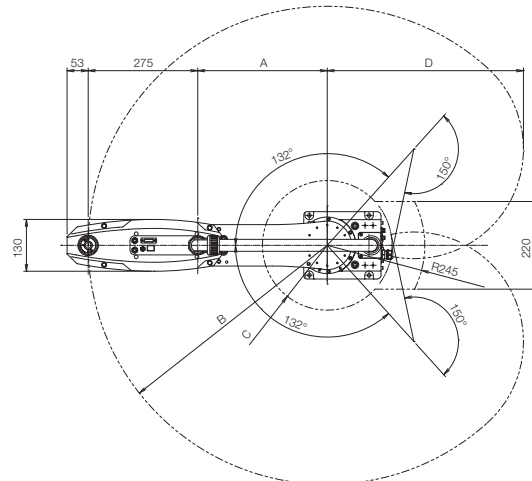
Specifications

Item	Unit	RH-6CRH6020	RH-6CRH7020
IP rating		IP20	
Environment		Standard	
Installation posture		On floor	
Connected controller		CR800-CHD	
Structure		Horizontal articulated robot	
Degree of freedom		4	
Load	Rating	kg	2
	Maximum	kg	6
Max. reach (Arm No. 1 + Arm No. 2)	mm	600	700
Arm length	Arm No. 1	mm	325
	Arm No. 2	mm	425
Operating range	J1	Degree	264 (±132)
	J2	Degree	300 (±150)
	J3 (Z)	mm	200
	J4 (θ)	Degree	720 (±360)
Maximum speed*1	J1	Degree/s	420
	J2	Degree/s	720
	J3	mm/s	1100
	J4	Degree/s	2500
	J1+J2	mm/s	7800
Pose repeatability	X-Y composite	mm	±0.02
	J3 (Z)	mm	±0.01
	J4 (θ)	Degree	±0.01
Ambient temperature	°C	0 to 40	
Allowable inertia	Rating	kgm ²	0.01
	Maximum	kgm ²	0.12
Mass	kg	17	18
Tool wiring		15 points, D-SUB	
Tool pneumatic pipes		Φ6 × 2, Φ4 × 1	
Brake		J1, J2 axes (without brake) J3, J4 axes (with brake)	

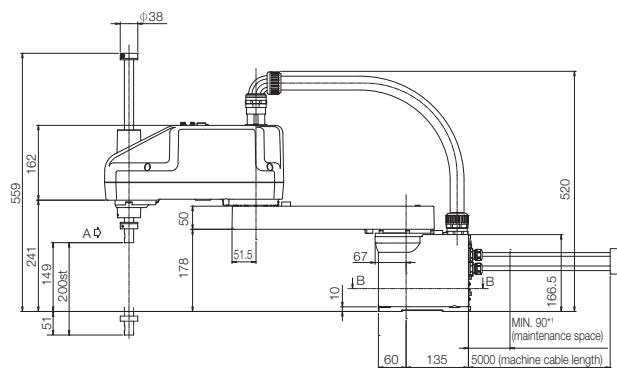
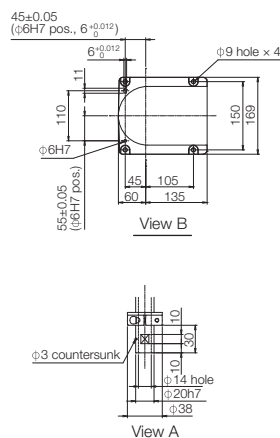


RH-6CRH

Operating range



External dimensions



*1: This is the space required for battery replacement, and indicates the dimensions including the minimum bending radius of the machine cable.

Model	A	B	C	D
RH-6CRH6020	325	R600	R162.6	492.5
RH-6CRH7020	425	R700	R232	559.4

*1: The values are taken when the robot is in MvTune2 (high-speed operation mode). Additionally, the values are taken under load conditions where no effect comes from automatic speed compensation due to the load mass.

MELFA RH-10CRH

Horizontal 10 kg Type

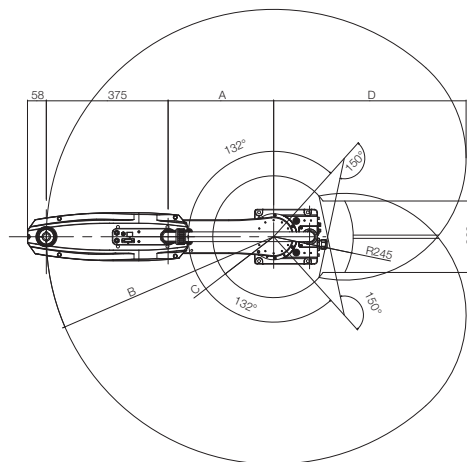
Specifications

Item		Unit	RH-10CRH60XX		RH-10CRH70XX		RH-10CRH80XX	
IP rating			IP20					
Environment			Standard					
Installation posture			On floor					
Connected controller			CR800-C2HD					
Structure			Horizontal articulated robot					
Degree of freedom			4					
Load	Rating	kg	5					
	Maximum	kg	10					
Max. reach (Arm No. 1 + Arm No. 2)		mm	600		700		800	
Arm length	Arm No. 1	mm	225		325		425	
	Arm No. 2	mm	375					
Operating range	J1	Degree	264 (±132)					
	J2	Degree	300 (±150)					
	J3 (Z)	mm	XX=20:200 / XX=30:300					
	J4 (θ)	Degree	720 (±360)					
Maximum speed*1	J1	Degree/s	420					
	J2	Degree/s	720					
	J3	mm/s	1100					
	J4	Degree/s	2700					
	J1+J2	mm/s	9100		9840		10570	
Pose repeatability	X-Y composite	mm	±0.02				±0.025	
	J3 (Z)	mm	±0.01					
	J4 (θ)	Degree	±0.01					
Ambient temperature		℃	0 to 40					
Allowable inertia	Rating	kgm ²	0.02					
	Maximum	kgm ²	0.3					
Mass*2		kg	20				21	
Tool wiring			15 points, D-SUB					
Tool pneumatic pipes			Φ6 × 2, Φ4 × 1					
Brake			J1, J2 axes (without brake) J3, J4 axes (with brake)					

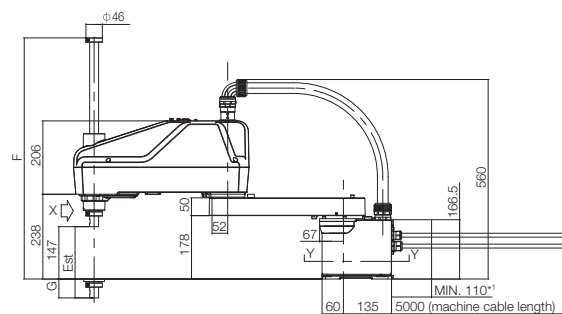
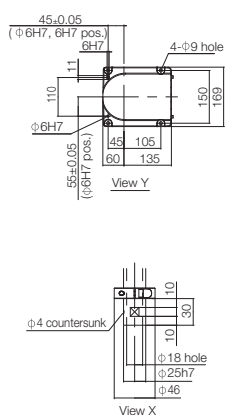


RH-10CRH

Operating range



External dimensions



*1: Dimensions including the minimum bending radius for the machine cable.

Model	A	B	C	D	E (J3 stroke)	F	G
RH-10CRH60XX	225	R600	R212.4	525.6	200/300	577/677	53/153
RH-10CRH70XX	325	R700	R187.5	592.5	200/300	577/677	53/153
RH-10CRH80XX	425	R800	R212.6	659.4	200/300	577/677	53/153

*1: The values are taken when the robot is in MvTune2 (high-speed operation mode). Additionally, the values are taken under load conditions where no effect comes from automatic speed compensation due to the load mass.

*2: The weight of the machine cable is not included.

MELFA RH-20CRH

Horizontal 20 kg Type

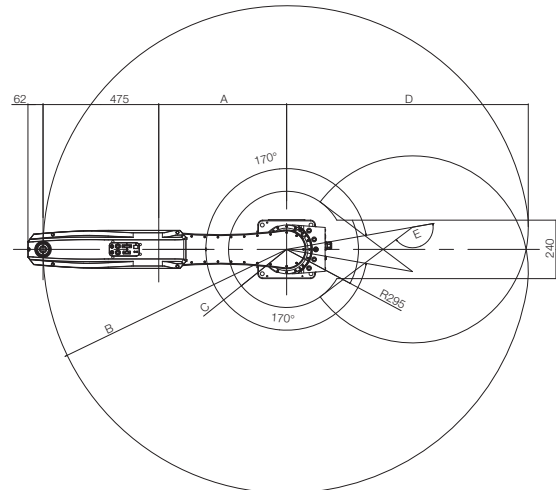
Specifications

Item	Unit	RH-20CRH8542	RH-20CRH10042
IP rating		IP20	
Environment		Standard	
Installation posture		On floor	
Connected controller		CR800-C2HD	
Structure		Horizontal articulated robot	
Degree of freedom		4	
Load	Rating	kg	10
	Maximum	kg	20
Max. reach (Arm No. 1 + Arm No. 2)	mm	850	1000
Arm length	Arm No. 1	mm	375
	Arm No. 2	mm	525
Operating range	J1	Degree	340 (±170)
	J2	Degree	290 (±145)
	J3 (Z)	mm	420
	J4 (θ)	Degree	720 (±360)
Maximum speed*1	J1	Degree/s	375
	J2	Degree/s	600
	J3	mm/s	2300
	J4	Degree/s	1600
Pose repeatability	J1+J2	mm/s	10530
	X-Y composite	mm	±0.025
	J3 (Z)	mm	±0.01
	J4 (θ)	Degree	±0.01
Ambient temperature	°C	0 to 40	
Allowable inertia	Rating	kgm ²	0.05
	Maximum	kgm ²	1.0
Mass*2	kg	54	57
Tool wiring		15 points, D-SUB. 9 points, D-SUB	
Tool pneumatic pipes		Φ8 × 2, Φ6 × 2	
Brake		J1, J2 axes (without brake) J3, J4 axes (with brake)	

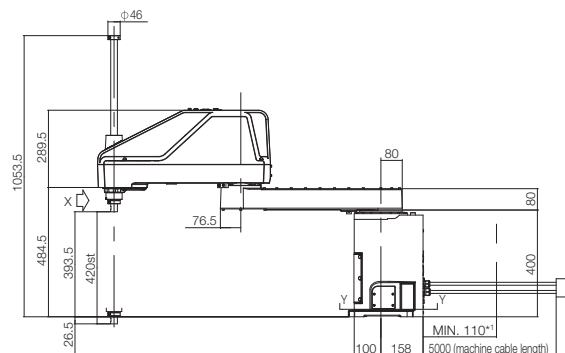
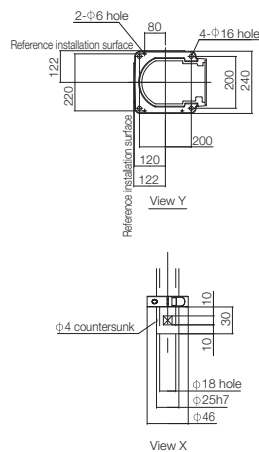


RH-20CRH

Operating range



External dimensions



*1: Dimensions including the minimum bending radius for the machine cable.

Model	A	B	C	D	E
RH-20CRH8542	375	R850	R221	844.3	145°
RH-20CRH10042	525	R1000	R238.5	992	153°

*1: The values are taken when the robot is in MvTune2 (high-speed operation mode). Additionally, the values are taken under load conditions where no effect comes from automatic speed compensation due to the load mass.

*2: The weight of the machine cable is not included.

Controller specifications

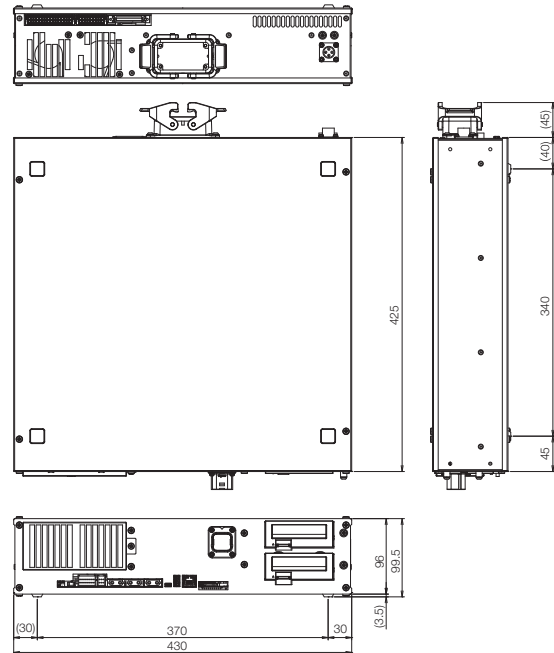
MELFA Controller CR800

Stand-alone robot controller
Robot controller can be used for centralized control.



CR800-CVD
CR800-12CVD
CR800-CHD
CR800-C2HD

External dimensions



Specifications

Item	Unit	CR800
Number of axes controlled		Vertical articulated robot: 6 axes at a time (Up to 8 axes can be added.) Horizontal articulated robot 4 axes at a time (Up to 8 axes can be added.)
Robot language		MELFA-BASIC V, VI
Memory capacity	Number of teaching points	39000
	Number of steps	78000
	Number of programs	512
External input/output	General-purpose I/O	32 inputs/32 outputs 2D-TZ368 (sink type) is attached at the time of shipment. The 2D-TZ378 (source type) is installed from the factory in the S15 with special specifications
	Dedicated I/O	Assigned to general-purpose I/O
	Emergency stop input	1 (Redundant)
	Door switch input	1 (Redundant)
	Mode selector switch input *1	1 (Redundant)
	Emergency stop output	1 (Redundant)
	Mode output	1 (Redundant)
	Robot error output	1 (Redundant)
	Synchronization of additional axes	1 (Redundant)
Interface	Encoder input	2
	Additional axis, force sensor interface	1 (SSCNET III/H)
	Remote I/O	1 (Compatible with Ver. 1.0/2.0)
	USB	1 (Ver. 2.0 High Speed device functions only. USB mini-B)
	Ethernet	1 (For user: 1000BASE-T/100BASE-TX/10BASE-T) 1 (For T/B: 100BASE-TX/10BASE-T) SLMP, CC-Link IE Field Basic, and Modbus TCP
	Extension slot	2 *2
	SD memory card slot	1 (For extended memory)
	RS-422	1 (Dedicated T/B)
Ambient temperature		°C
Ambient humidity		%RH
Power supply	Input voltage range *3	V
	Power capacity *4	kVA
External dimensions		mm
Mass		kg
Structure		Self-contained/open structure (can be placed vertically or horizontally) [IP20]
Grounding *5		Ω

*1: Mode selector switch is to be provided by the customer.

*2: For installing optional interface. The 2D-TZ368 is pre-installed in slot 1 of 2. The 2D-TZ378 is pre-installed in the S15 which has special specifications. Two connectors for the 2D-TZ368 and 2D-TZ378 are included. The cable is to be supplied and connected by the customer.

*3: Power supply voltage variability is within 10%.

*4: The power capacity is the recommended value. The power capacity does not include the rush current when the power is turned ON. The power capacity is a guideline.

*5: Grounding work is to be performed by the customer.



Options

Mechanical options

○: Supported, △: Partially supported, -: Not supported

Name	Model	RV-8CRL	RV-12CRL	RH-3/6CRH	RH-10/20CRH	Specifications
Hand input-output cable	1F-HC1000S-43	-	○	-	-	Robot side: Connector, Hand side: Wire
Machine cable (replaceable type)	1F-□□UCBL-42	-	-	○	-	Fixed type: 3 m, 10 m, 15 m, 20 m. "□□" indicates the cable length (3 m, 10 m, 15 m, or 20 m)
	1F-□□UCBL-43	○	○	-	-	Fixed type: 10 m, 15 m, 20 m. "□□" indicates the cable length (10 m, 15 m, or 20 m)
Machine cable (replacement) (Bending)	1F-□□UCBL-42	-	-	○	-	Flexible type: 10 m, 15 m, 20 m. "□□" indicates the cable length (10 m, 15 m, or 20 m)
	1F-□□UCBL-43	○	○	-	-	Flexible type: 10 m, 15 m, 20 m. "□□" indicates the cable length (10 m, 15 m, or 20 m)
	1F-□□UCBL-45	-	-	-	○	Flexible type: 10 m, 15 m, 20 m. "□□" indicates the cable length (10 m, 15 m, or 20 m)
J1 axis operating range change	1F-DH-42J1	-	○	-	-	The customer is responsible for purchasing the stopper and setting the limits to 150 degrees on the + and - sides.

Controller options

○: Supported, △: Partially supported, -: Not supported

Name	Model	RV-8CRL	RV-12CRL	RH-3/6CRH	RH-10/20CRH	Specifications
Simple teaching box	R32TB	○	○	○	○	Cable length: 7 m
	R32TB-15	○	○	○	○	Cable length: 15 m
High performance teaching box		○	○	○	○	Cable length: 7 m. For a length longer than 7 m, use a teaching box extension cable.
Parallel input-output unit	(Sink type) 2A-RZ361	○	○	○	○	Input: 32 points/Output: 32 points
	(Source type) 2A-RZ371	○	○	○	○	Insulated output signal (Output signal: 0.1 A/24 V/point) Insulated input signal (Input signal: 7 mA/24 V/point)
External input-output cable (5 m, 15 m)		○	○	○	○	CBL05: 5 m / CBL15: 15 m Used to connect the external I/O unit to peripheral equipment.
Parallel input-output interface	(Sink type) 2D-TZ368	○	○	○	○	Input: 32 points/Output: 32 points
	2D-TZ378	○	○	○	○	Insulated output signal (Output signal: 0.1 A/24 V/point) Insulated input signal (Input signal: 9 mA/24 V/point)
External input-output cable (5 m, 15 m)		○	○	○	○	CBL05: 5 m CBL15: 15 m Used to connect the external I/O interface to the peripheral.
Controller protection box		○	○	○	○	IP54
MELSOFT RT ToolBox3		○	○	○	○	With simulation function
MELSOFT RT ToolBox3 mini		○	○	○	○	Simple
MELSOFT RT ToolBox3 Pro		○	○	○	○	Professional
SD memory card		○	○	○	○	Capacity: 2 GB
CC-Link interface		○	○	○	○	Supports only intelligent device stations and local stations.
Network base card (CC-Link IE TSN interface)		○	○	○	○	Communication interface for HMS Anybus CompactCom module. HMS CC-Link IE TSN module (AB6714-C-106) is to be provided by the customer.
Network base card (EtherNet/IP interface)		○	○	○	○	Communication interface for HMS Anybus CompactCom module. HMS EtherNet/IP module (AB6704-E-161) is to be provided by the customer.
Network base card (PROFINET IO interface)		○	○	○	○	Communication interface for HMS Anybus CompactCom module. HMS PROFINET IO module (AB6705-E-210) is to be provided by the customer.
Network base card (CC-Link IE Field interface)		○	○	○	○	Communication interface for HMS Anybus CompactCom module. HMS CC-Link IE Field module (AB6709-C-118) is to be provided by the customer.
Network base card (EtherCAT interface)		○	○	○	○	Communication interface for HMS Anybus CompactCom module. HMS EtherCAT module (AB6707-E-224) is to be provided by the customer.

Functional options

○: Supported, △: Partially supported, -: Not supported

Name	Model	RV-8CRL	RV-12CRL	RH-3/6CRH	RH-10/20CRH	Specifications
Force sensor set	4F-FS002H-W200	○	○	-	-	Set of equipment required for force control function, including force sensor, interface unit, and support software
	4F-FS002H-W1000	○	○	-	-	
MELFA-3D Vision 3.0	3F-53U-WINM	○	○	○	○	Software that connects a compact 3D vision sensor for robots to measure and recognize parts.
Safety option	4F-SF002-01	○	○	○	○	Devices required for safety functions.
	4F-SF003-05	○	○	○	○	

Expanded software functions

○: Supported, △: Partially supported, -: Not supported

Name	Model	RV-8CRL	RV-12CRL	RH-3/6CRH	RH-10/20CRH	Specifications
iQ Care MELFA Support *1	RA-1W00M**	○	△ *2	○	△ *2	One-year additional warranty package
	RA-2W00M**	○	△ *2	○	△ *2	Two-year additional warranty package
	RA-0W11M**	○	△ *2	○	△ *2	Simple inspection service package
	RA-0W21M**	○	△ *2	○	△ *2	Precise inspection service package
	RA-1W11M**	○	△ *2	○	△ *2	One-year additional warranty & simple inspection service package
	RA-1W21M**	○	△ *2	○	△ *2	One-year additional warranty & precise inspection service package

*1: ** refers to the code for the region the product was purchased in (two alphabetic characters).
*2: The predictive maintenance function of the monitoring service is not supported.

[illegible]

Age Group	Percentage
18-24	10%
25-34	15%
35-44	20%
45-54	25%
55-64	30%
65-74	35%
75-84	40%
85+	45%

[illegible]

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